

# Scalable Corrective Security-Constrained Economic Dispatch (SCED) Considering Conflicting Contingencies

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# Outline

- Introduction
- Literature review
- Problem formulation
- Solution methodology – Contingency filtering
- Performance enhancements
- Numerical results

## Our recent publication

- a. Y. Yu and P. B. Luh, “Scalable Corrective Security-constrained Economic Dispatch Considering Conflicting Contingencies,” *International Journal of Electrical Power and Energy Systems*, vol. 98, pp. 269-278, June 2018.

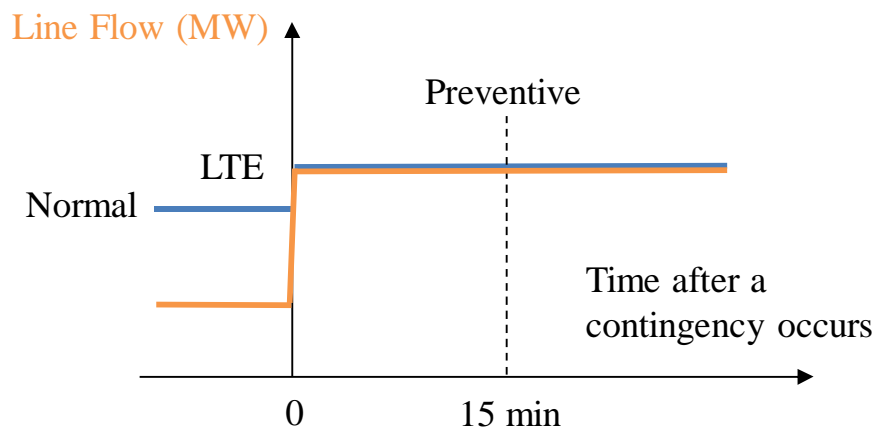
# Introduction

- Preventive SCED <sup>[1]</sup>: One set of ED decisions feasible for the base case and all “ $N - 1$ ” transmission contingencies
- Corrective SCED <sup>[2]</sup>: Base-case ED decisions can be adjusted within a unit’s ramping capability after each contingency
- Improved corrective SCED <sup>[3]</sup>
  - Preventive SCED to capture the system status right after a contingency
  - Corrective SCED to model adjustment of post-contingency flows
    - To be within Long-Term Emergency (LTE) ratings in 15 min after a contingency <sup>[4]</sup> <sup>[5]</sup>

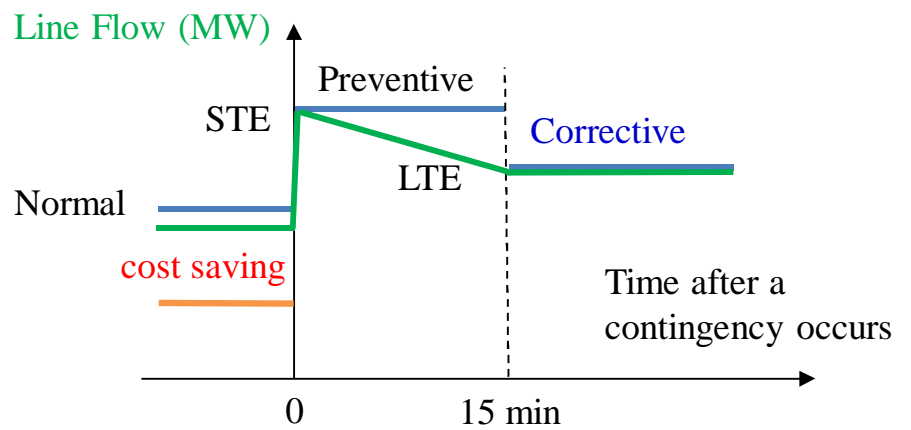
1. Alsac O, Stott B. Optimal load flow with steady-state security. *IEEE Trans Power Ap Syst* 1974;PAS-93(3):745–51.
2. Monticelli A, Pereira MVF, Granville S. Security-constrained optimal power flow with post-contingency corrective rescheduling. *IEEE Trans Power Syst* 1987;2(1):175–80.
3. Capitanescu F, Wehenkel L. Improving the statement of the corrective security constrained optimal power-flow problem. *IEEE Trans Power Syst* 2007;22(2):887–9.
4. NERC, System Operating Limit Definition and Exceedance Clarification, 2015. [Online]. Available: [http://www.nerc.com/pa/Stand/Prjct201403RvsnstoTOPandIROStndrds/2014\\_03\\_fifth\\_posting\\_white\\_paper\\_sol\\_exceedance\\_20150108\\_clean.pdf](http://www.nerc.com/pa/Stand/Prjct201403RvsnstoTOPandIROStndrds/2014_03_fifth_posting_white_paper_sol_exceedance_20150108_clean.pdf)
5. ISO New England Operating Procedure No. 19 – Transmission Operations, 2016. [Online]. Available: [http://www.iso-ne.com/rules\\_proceeds/operating/isone/op19/op19\\_rto\\_final.pdf](http://www.iso-ne.com/rules_proceeds/operating/isone/op19/op19_rto_final.pdf)

- Advantages of corrective SCED – Higher efficiency
  - More efficient utilization of the transmission grid
  - Explicit modeling of generator contingencies, instead of reserves
- Difficulties
  - Corrective SCED is more complex than preventive SCED
    - Large numbers of post-contingency ED decisions and constraints, one set per contingency
  - Strict time limit of real-time dispatch
  - Different types of infeasible contingencies, especially “conflicting contingencies”

(Pure) Preventive SCED



Improved Corrective SCED



# Literature review

- Direct approach
  - Directly solves the problem with all possible contingencies
  - Large numbers of decision variables and constraints
- Contingency filtering [6] [7] [8]
  - Starts the base-case model, and then iteratively adds selected active contingencies to revise the solution
  - Most contingencies were not active at the optimum, so select possibly active ones by ranking all contingencies:
    - Based on the severity index (2-norm of weighted constraint violations) [6]
    - Via the non-dominated contingency (comparing constraint violations) [7]
    - Based on the rescheduling index (the minimum of the maximal controllable redispatch value) [8]

6. Stott B, Alsac O, Monticelli AJ. Security analysis and optimization. *Proc IEEE* Dec. 1987;75(12):1623–44

7. Capitanescu F, Wehenkel L. A new iterative approach to the corrective security-constrained optimal power flow problem. *IEEE Trans Power Syst* Nov. 2008;23(4):1533–41.

8. Jiang Q, Xu K. A novel iterative contingency filtering approach to corrective security-constrained optimal power flow. *IEEE Trans Power Syst* 2014;29(3):1099–109.

- Benders decomposition [9] [10] [11] [12]
  - Divides the CCED problem into a base-case master problem and multiple contingency subproblems
    - For a given base-case ED, “violated cuts” derived from subproblems and added to the master problem
  - Enhancements including [parallel computing](#)
  - Solved [the Polish 2383-bus system](#) with all transmission contingencies considering DC power flow within [10 minutes](#) [12]
- [Remaining difficulties](#)
  - A faster approach is desired for practical use (< 2~3 minutes)
  - How to manage infeasible contingencies? (To discuss later)

9. Capitanescu F, Ramos JLM, Panciatici P, Kirschen D, Marcolini AM, Platbrood L, et al. State-of-the-art, challenges, and future trends in security constrained optimal power flow. *Electr Power Syst Res* 2011;81(8):1731–41.
10. Peng P and Chang S, “Inclusion of Post-Contingency Actions in Security Constrained Scheduling,” FERC’s 2013 Technical Conference.
11. Chang S, et al., Maximizing transmission efficiency using the National Grid Electricity Balancing System. *2015 IEEE Power & Energy Society General Meeting*, Denver, CO, 2015, pp. 1-5.
12. Liu Y, Ferris MC, Zhao F. Computational study of security constrained economic dispatch with multi-stage rescheduling. *IEEE Trans Power Syst* 2015;30(2):920–9.

# Problem Formulation

- SCED
  - A single time period optimization
  - Executed periodically in real-time (e.g., every 5 minutes)
  - Determines the MW level for each **online** unit
  - Uses DC power flow – **Performance tradeoff vs AC power flow**
- Model both “ $N - 1$ ” transmission and generator contingencies
  - $L$  lines,  $I$  buses, and  $K$  units
  - $L + K + 1$  sets of ED decisions
  - Contingency index:  $c$ 
    - $c = 0$  – Base case
    - $c = 1, \dots, L$  – Transmission contingencies
    - $c = L + 1, \dots, L + K$  – Generator contingencies

- Formulation

To minimize the base-case ED cost

$$\min_k \mathring{a} C_k(p_{k,0})$$

s.t.

Transmission

$$- \underbrace{f_{l,c}^{\max}}_{\text{When } c=0, \text{ normal rating; otherwise, LTE rating}} \leq f_{l,c} = \frac{q_{a(l),c} - q_{b(l),c}}{X_l} \leq f_{l,c}^{\max}, \quad l, c \in L$$

Generator capacity

$$p_k^{\min} \leq p_{k,c} \leq p_k^{\max}, \quad k, c \in TC+k$$

Nodal flow balance

$$\mathring{a} p_{k,c} - D_i = \mathring{a} f_{l,c} - \mathring{a} f_{l',c}, \quad i, c \in F(i); k \in L$$

$l: a(l)=i, l' \in L$        $l: b(l)=i, l' \in L$

(Post-contingency) redispatch

$$p_{k,0} - \underbrace{D_{k,c}}_{\text{15-min ramp rate for transmission contingencies}} \leq p_{k,c} \leq p_{k,0} + D_{k,c}, \quad k, c \in L+k$$

10-min ramp rate for generator contingencies (ISO New England uses 10-min reserves as a buffer)

Contingency-level constraints

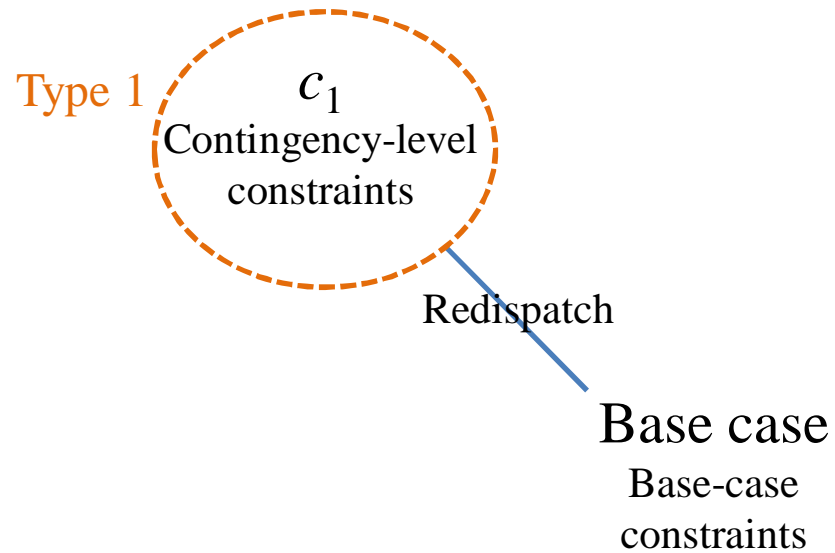
Coupling constraints

- A large-sized LP problem

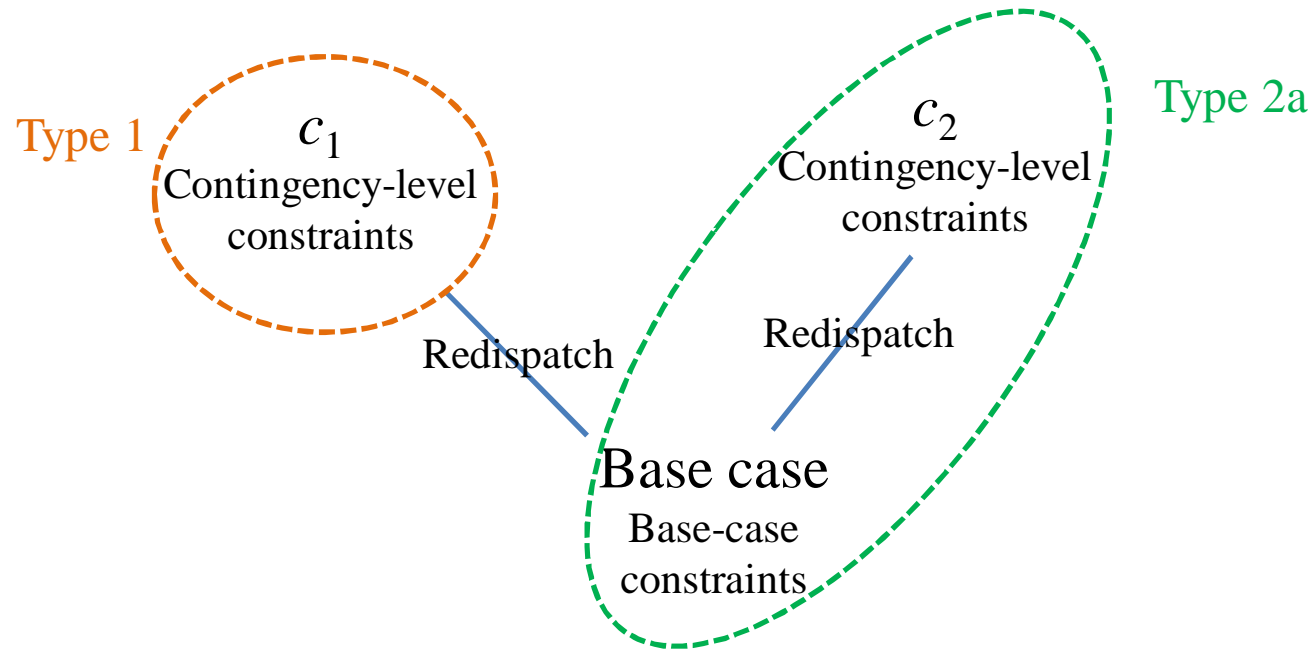
- A large number of ED decisions and corresponding constraints
- Post-contingency ED decisions loosely coupled with the base case



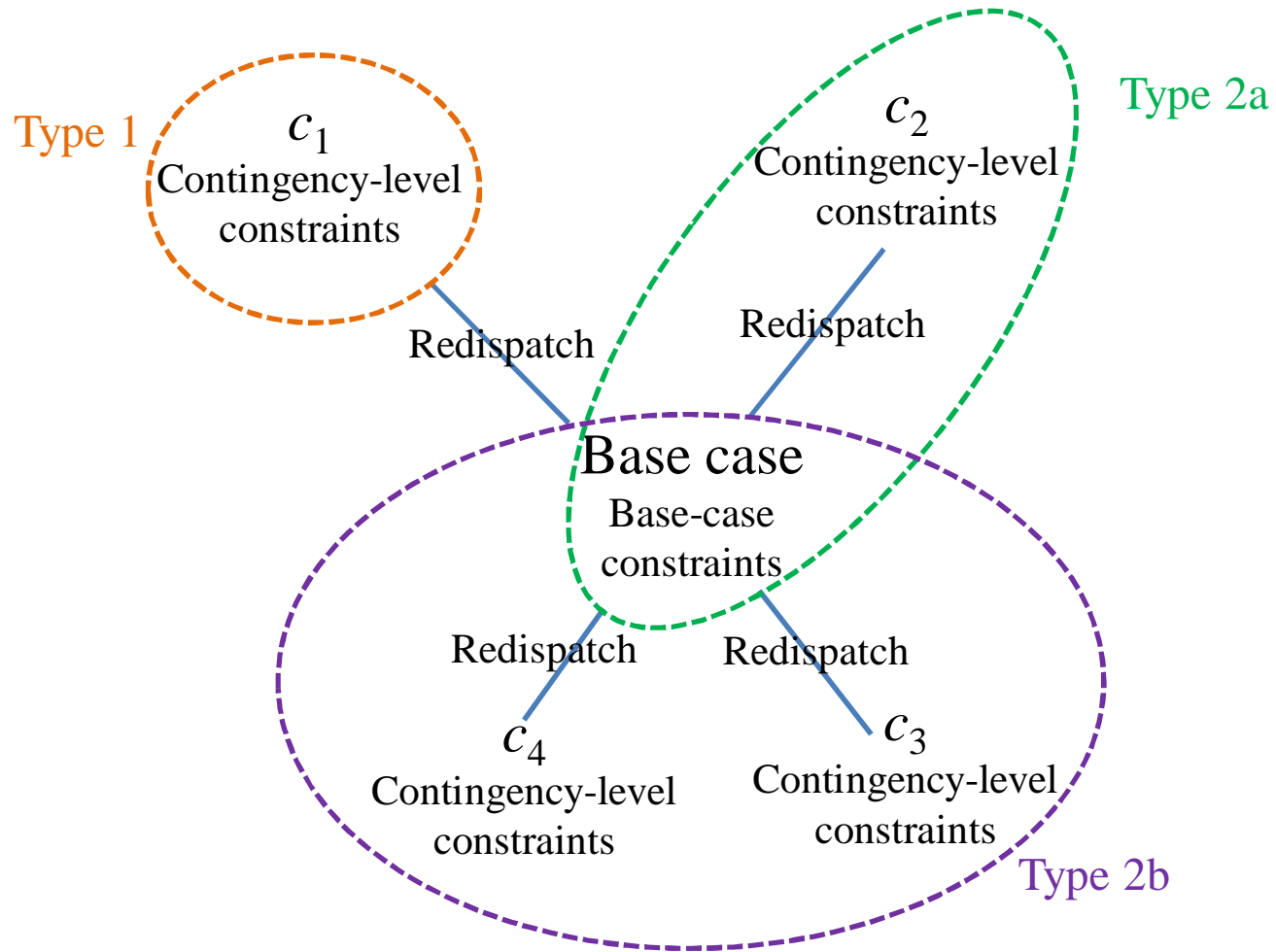
- Infeasible contingencies
  - Defined in our paper [a] based on the formulation not on an algorithm



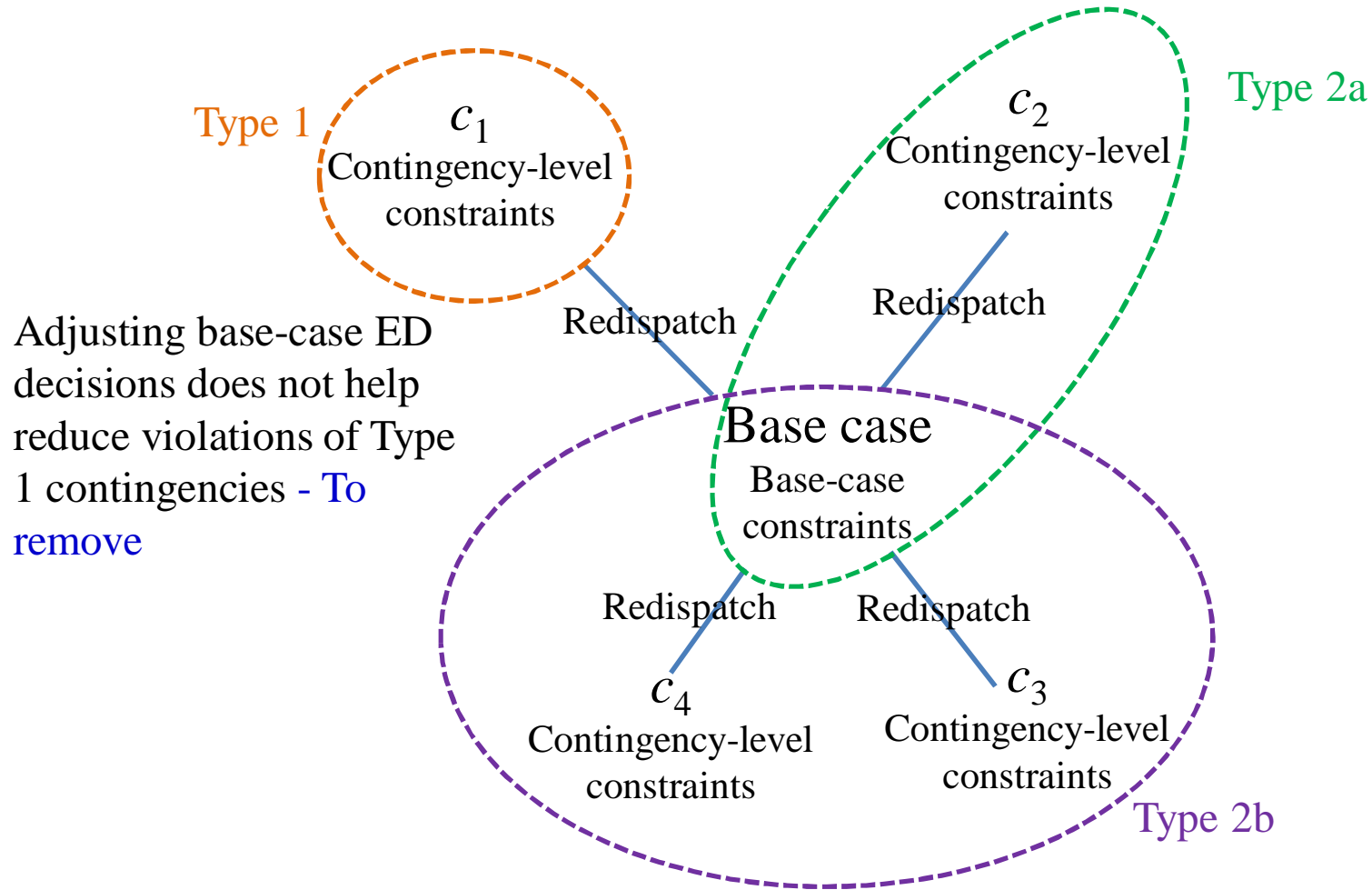
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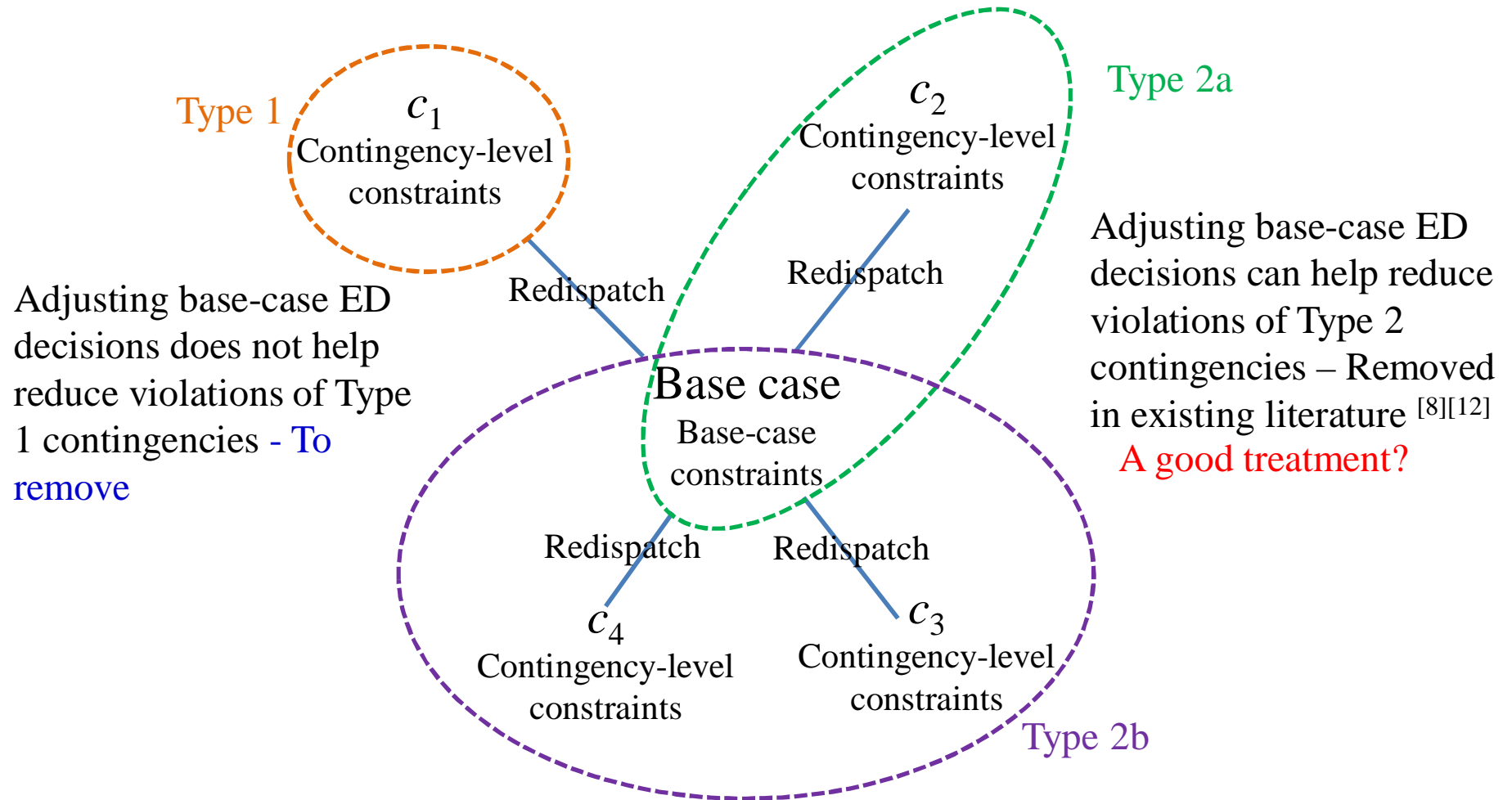


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- Liu Y, Ferris MC, Zhao F. Computational study of security constrained economic dispatch with multi-stage rescheduling. *IEEE Trans Power Syst* 2015;30(2):920–9.

# Methods to overcome the difficulties

Scalable

- Decomposition and coordination with contingency filtering
- Warm-start method of creating subproblem models
- Parallel computing

Managing  
infeasible  
contingencies

# Solution methodology – Contingency filtering

- Decomposition and coordination

- A master problem with the base case and active contingencies
- Subproblems for candidate contingencies
- Starts with the base-case model, and then iteratively adds identified active contingencies to revise the solution

- Key points of our approach

- The master problem and subproblems are formulated linearly
- By introducing penalty terms for individual contingencies, multiple conflicting contingencies can be simultaneously identified
- **Keep or remove** Type 2 contingencies based on the operator's choice
  - **Keep Type 2 contingencies** to minimize the overall violation
  - Or remove them for reduced base-case cost
- Identify active contingencies in subproblems w/o ranking them
  - Linear Programming (LP) should be able to solve the master problem with all active contingencies

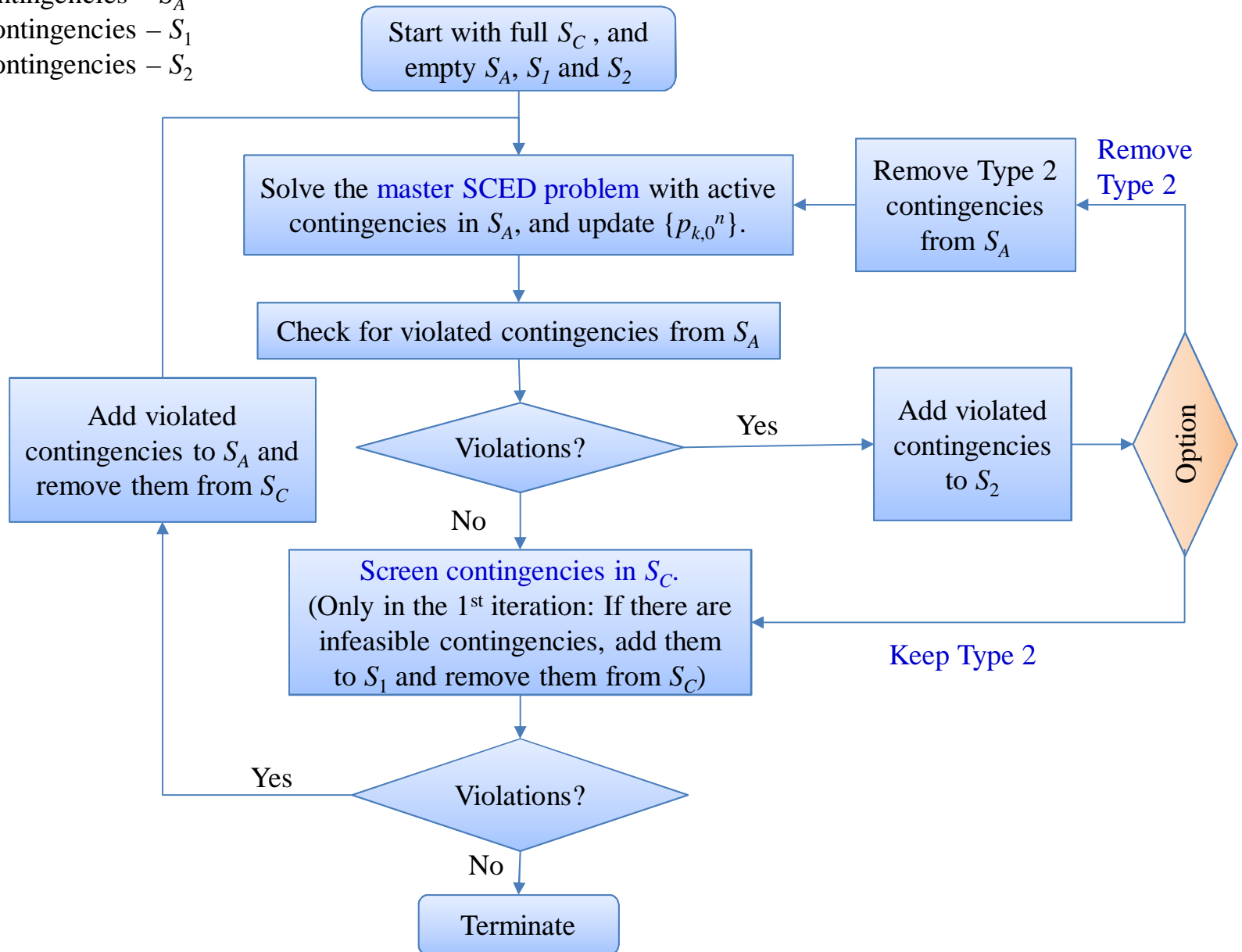
Sets:

Set of candidate contingencies –  $S_C$

Set of active contingencies –  $S_A$

Set of Type 1 contingencies –  $S_1$

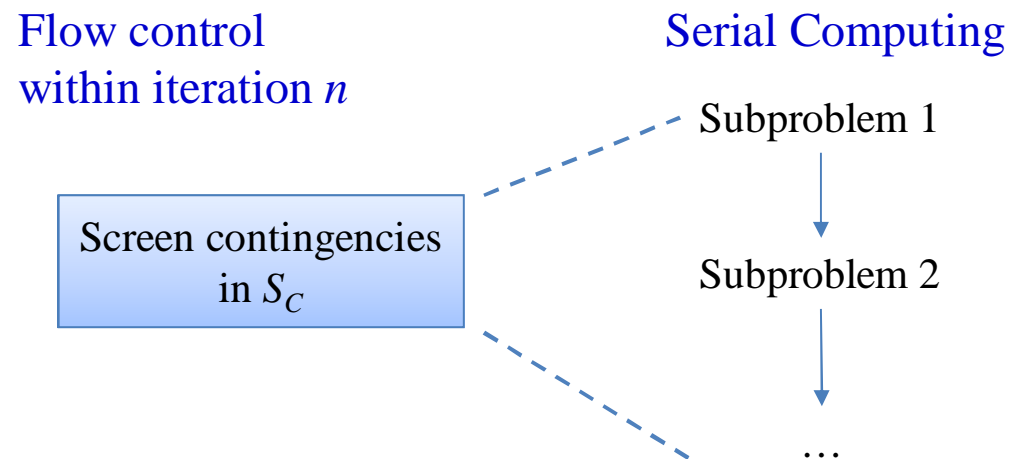
Set of Type 2 contingencies –  $S_2$



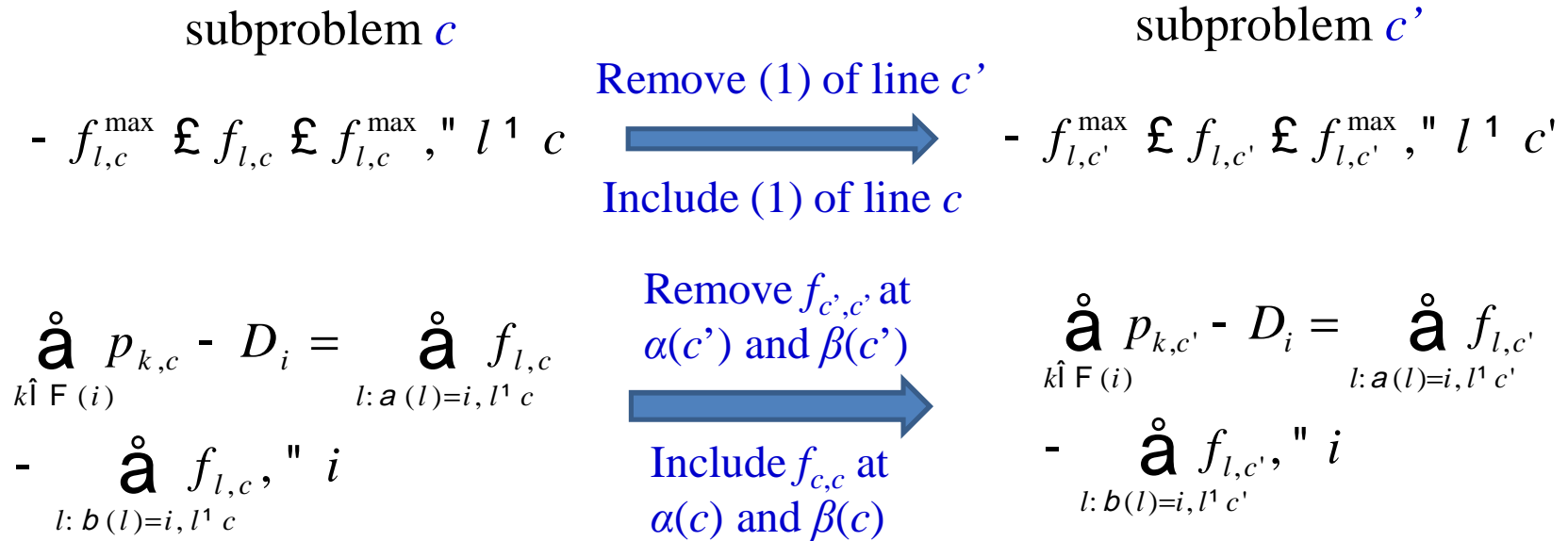


# Performance enhancements

- Warm-start method of creating subproblem models between different contingencies
  - **Overhead of creating models for all subproblems**
    - Thousands of subproblem models at each iteration
    - The overhead time of creating a new model for each subproblem can be comparable to or even more than the CPU time of solving each subproblem
  - Explore the flow control and subproblem structures



- Analyze two transmission contingencies



Other constraints remain the same

- We create only the first subproblem and then make the fewest possible modifications from one subproblem to another

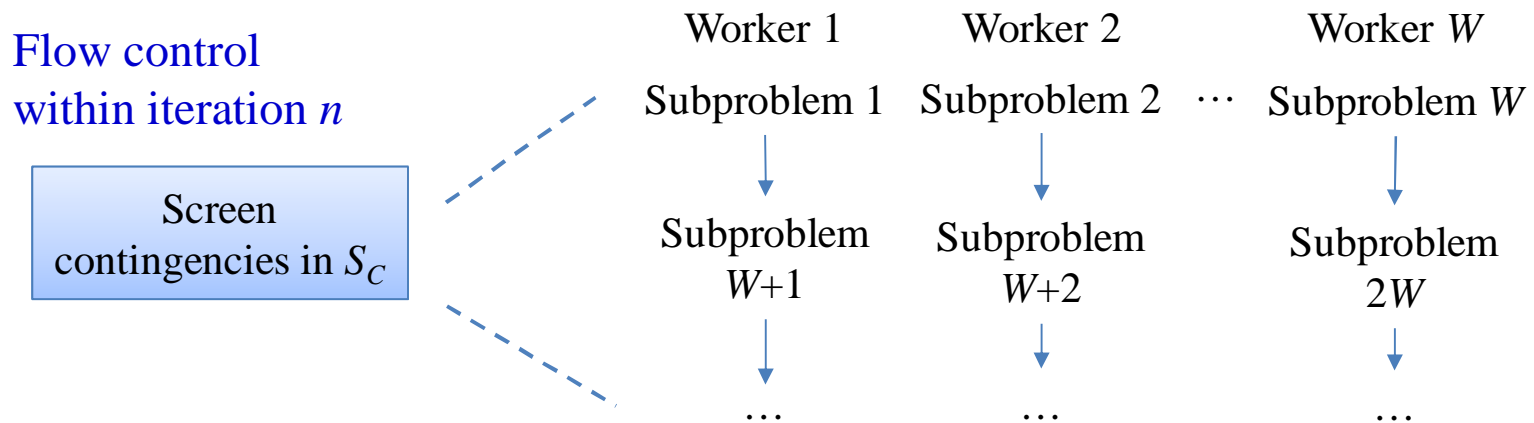
- Comparison of # of operations
  - Take the 1st iteration for example. The others directly reuse existing models w/o creating new ones in our method

Constraints	Creating all subproblem models	Our warm-start method	
	# of constraints created	# of constraints created	# of constraints modified
Transmission	$2(L - 1) \times L$	$2(L - 1)$	$4 \times (L - 1)$
Generator capacity	$2K \times L$	$2K$	0
Nodal flow balance	$I \times L$	$I$	$4 \times (L - 1)$
Redispatch	$2K \times L$	$2K$	0

- Similar for generator contingencies

- Parallel computing

- Checking violations of a large number of contingencies in parallel



- Default multithreaded parallelization in CPLEX or Gurobi can be used to solve each subproblem
- High-level parallelism via CPLEX remote object [13], [14]
  - Communication through MPI
  - Exchanging a small amount of information  $\{p_0^n\}$  and  $c$
- Warm-start method implemented in a group-wise fashion

13. CPLEX 12.6.1 Manual

14. Rux S. Applications and Use Cases of the CPLEX Remote API. IBM Software Group, 2014. [Online]. Available: <http://www-01.ibm.com/support/docview.wss?uid=swg27044403>

## Example - Polish 2383-bus system at winter peak

- Summary of the realistic Polish 2383-bus system <sup>[15]</sup>
  - 327 conventional units – All assumed online
    - One price block each
    - 262 of them have zero costs
  - 2896 lines: Normal and LTE ratings
  - Data at the winter peak

15. Polish 2383-bus system at winter peak (case2383wp). [Online]. Available: <http://www.neos-guide.org/content/optimal-power-flow>

- Improved reliability when keeping Type 2 contingencies
  - With 96 transmission and 4 generator contingencies
  - $M = \$5,000/\text{MWh}$
  - Simulation: After optimization, fix the base-case decisions and check violations of all (Type 2) contingencies again
  - Implemented with OPL on a PC laptop

		Keep Type 2	Remove Type 2
Optimization	Wall clock time (s)	36	39
	Optimization cost (k\$)	4,244.24	1,855.99
	Penalty cost (k\$)	2,326.11	0
Simulation	Base-case ED cost (k\$)	1,918.12	1,855.99
	Simulation cost (k\$)	4,244.24	6,917.39
	Penalty cost (k\$)	2,326.11	5,061.40

Tradeoff between reliability and the base-case ED cost

- Computational performance
  - With all 2896 “ $N - 1$ ” transmission contingencies
  - UConn High Performance Computing (HPC) cluster
    - Using 1 node with 24 cores; SLURM and Linux
  - CPLEX 12.6.1.0 C++ API

Configuration	a	b	c
Subproblem models	Creating all	Warm-start	Warm-start
Parallelism	Multi-threaded	Multi-threaded	Remote object
Wall clock time	21min42s	7min53s	<b>1min51s</b>
CPU time	16min07s	7min52s	1min45s
Overhead time	5min35s	<b>1s</b>	6s
Overhead/CPU time ratio	34.64%	0.21%	5.71%
Speedup ratio of wall clock time	1	2.75	11.73

- Overhead is significantly reduced to a negligible level
- **Potential for practical use in real-time operations**

# Conclusion

- Our new approach is scalable for corrective SCED problems
  - Decomposition and coordination with contingency filtering
  - Warm-start method of creating subproblem models
  - Parallel computing
- Instead of always removing conflicting contingencies as presented in existing literature, we provide system operators with an important option to keep them for increased reliability
  - Validated by simulation results
- Testing against the Polish 2383-bus system demonstrates the computationally efficiency for practical use in real-time



# Our recent publication

- a. Y. Yu and P. B. Luh, “Scalable Corrective Security-constrained Economic Dispatch Considering Conflicting Contingencies,” *International Journal of Electrical Power and Energy Systems*, vol. 98, pp. 269-278, June 2018.

# Thank you!

**For more information:**

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# Backup slides

- Master problem

$$\min_{\substack{\hat{a} \\ \hat{e}_k}} C_k(p_{k,0}) + M \underbrace{\hat{a} \hat{a} (s_{k,c}^U + s_{k,c}^D)}_{\hat{c} \in S_A, k^1 c-L} = \min_{\substack{\hat{a} \\ \hat{e}_k}} C_k(p_{k,0}) + \hat{a} y_c \hat{u} \quad \hat{c} \in S_A, \hat{u}$$

s.t.

Relaxed redispatch constraints

$$p_{k,c} - s_{k,c}^U \leq p_{k,0} + D_{k,c}, \quad c \in S_A, \quad k^1 c-L, s_{k,c}^U \geq 0$$

$$p_{k,0} - D_{k,c} - s_{k,c}^D \leq p_{k,c}, \quad c \in S_A, \quad k^1 c-L, s_{k,c}^D \geq 0$$

Contingency-level constraints for  $c \in \{0\} \cup S_A$

- Penalty cost  $M$  should be large
  - Otherwise, feasible contingencies identified as Type 2
- Can identify multiple Type 2 contingencies at the same time
  - Penalty terms for individual contingencies (with index  $c$ )
- Among multiple Type 2b contingencies conflicting with each other, those can be violated with the lowest overall cost will be identified through optimization

- Contingency subproblems

- Formulated to check for violations in contingencies to identify possibly active ones as well as Type 1 contingencies

Subproblem for **transmission contingency**  $c$  given  $p_{k,0}^n$

$$v_c = \min_k \mathring{a} (s_{k,c}^U + s_{k,c}^D)$$

s.t.

$$p_{k,c} - s_{k,c}^U \leq p_{k,0}^n + D_{k,c}, \quad k \in \mathcal{K}, s_{k,c}^U \geq 0$$

$$p_{k,0}^n - D_{k,c} - s_{k,c}^D \leq p_{k,c}, \quad k \in \mathcal{K}, s_{k,c}^D \geq 0$$

Contingency-level constraints for  $c$

Subproblem of **generator contingency**  $c$  given  $p_{k,0}^n$

$$v_c = \min_{k \in \mathcal{K} \cup \{c-L\}} \mathring{a} (s_{k,c}^U + s_{k,c}^D)$$

s.t.

$$p_{k,c} - s_{k,c}^U \leq p_{k,0}^n + D_{k,c}, \quad k \in \mathcal{K} \cup \{c-L\}, s_{k,c}^U \geq 0$$

$$p_{k,0}^n - D_{k,c} - s_{k,c}^D \leq p_{k,c}, \quad k \in \mathcal{K} \cup \{c-L\}, s_{k,c}^D \geq 0$$

Contingency-level constraints for  $c$

- If  $v_c^* > 0$ ,  $c$  active;
- If  $v_c^* = 0$ ,  $c$  inactive;
- If subproblem infeasible,  $c$  is Type 1