Power system restoration through mixed integer linear programming

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Outline

- 1. Motivation and contributions
- 2. MILP approximation of AC power flow equations
- 3. Integer L-shaped method for power system restoration
- 4. Numerical results
- 5. Conclusions and future work

Motivation and ▷ contributions

MILP approximation of AC power flow equations

Integer L-shaped method for power system restoration

Numerical results

Conclusions and future work

Motivation and contributions

Blackouts and power system restoration

- \Box Ohio blackout of 2003
 - Initiated by fault of HV power line
 - 50 million affected, 11 deaths, \$6 billion
- \Box European blackout of 2006
 - Initiated by routine disconnection of HV power line
 - 10 million affected, 100 trains delayed
 - Forced operators to improve their resynchronization procedures
- \Box Chilean blackout of 2011
 - Initiated by fault at HV capacitor
 - Restoration delayed because of **procedural** and equipment issues

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Literature on power system restoration

- □ (Hou *et al.*, 2011) and (Liu *et al.*, 2012) propose a step-wise stategy based on achieving pre-specified milestones
- □ (Sun *et al.*, 2011) optimizes the startup strategy for generators considering only active power in a copper-plate model of the grid
- □ (Chou *et al.*, 2013) formulates a mixed-integer non-linear problem for restoration and provides solutions using an heuristic algorithm
- Coffrin and Van Hentenryck, 2014) solve the optimal restoration problem using a LP approximation of the AC power flow equations on a network with 266 components

Contributions

- We propose an MILP approximation of the AC power flow equations based on minimum square-error
 - LP relaxation is sufficient under scarcity of reactive power
 - MILP necessary under excess of reactive power
- □ We specialize the integer L-shaped method for solving optimal power system restoration on realistic instances
 - Stronger island-based no-good cuts
 - Hybrid Benders-no-good cuts
- We present numerical results for IEEE test systems and for the Chilean power grid with 3696 components (buses, branches, compensation, generators) – one order of magnitude larger than state-of-the-art

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Motivation and	ł
contributions	

MILP approximation of AC power flow ▷ equations

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MILP approximation of AC power flow equations

AC relaxations in power system restoration: an example



Is it possible to energize line 1-2?

Full AC answer: No, excess of reactive power

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AC relaxations in power system restoration: an example

Feasible domains for reactive power entering a terminal as a function of angle difference δ for:

- 1. the QC relaxation (Coffrin *et al.*, 2016)
- 2. LP approximation (cold-start LPAC, 5 intervals) (Coffrin and Van Hentenryck, 2014)
- 3. MILP approximation (5 intervals)



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Piece-wise linear approximations of continuous functions

 \Box (Toriello and Vielma, 2012): a partition *I* of the interest domain for the approximation and a set of slopes a_i and intercepts b_i

Problem: we have a continuous function $f : \mathbb{R}^n \to \mathbb{R}$ that we wish to approximate with a piecewise linear function $\hat{f} : \mathbb{R}^n \to \mathbb{R}$ defined as

$$\hat{f}(\boldsymbol{x}) := \boldsymbol{a}_i^T \boldsymbol{x} + b_i \text{ if } \boldsymbol{x}_i^L \preccurlyeq \boldsymbol{x} \preccurlyeq \boldsymbol{x}_i^U, i \in I,$$

 \Box Determine $x_i^L, x_i^U \ \forall i \in I \rightarrow$ equal **curvature** intervals

 \Box Determine $\boldsymbol{a}_i^T, b_i \ \forall i \in I \rightarrow$ solve:

$$\min_{\boldsymbol{a}, b} \quad \sum_{i \in I} \int_{[\boldsymbol{x}_i^L, \boldsymbol{x}_i^U]} (\boldsymbol{a}_i^T \boldsymbol{x} + b_i - f(\boldsymbol{x}))^2 d\boldsymbol{x}$$

s.t.
$$\boldsymbol{a}_i^T \boldsymbol{x} + b_i = \boldsymbol{a}_j^T \boldsymbol{x} + b_j \quad \forall x \in F(i, j), \forall (i, j) \in \mathcal{F}$$

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$$p_1(v_1, v_2, \delta) = v_1^2 g_{12} - v_1 v_2 g_{12} \cos(\delta) - v_1 v_1 b_{12} \sin(\delta)$$

$$q_1(v_1, v_2, \delta) = -v_1^2 b_{12} + v_1 v_2 b_{12} \cos(\delta) - v_1 v_2 g_{12} \sin(\delta)$$

- Linear approximation in terms of voltages
- Piece-wise linear approximation in terms of angle difference, only if necessary
- \Box Enforcing convexity or concavity depending on g_{12}, b_{12}



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- \Box Power transformers:
 - N-windding transformers $(N > 2) \rightarrow$ star model
 - Phase shifters \rightarrow adder to angle difference
 - Voltage tap-changers \rightarrow adder to voltage magnitude
- Shunt compensators: sectionalized and variable compensators (FACTS)
- □ Voltage-responsive loads:

$$p + s = P \cdot v^{\alpha}$$
$$q = Q \cdot v^{\beta} \cdot p / (P \cdot v^{\alpha})$$

Linear approximation of p + s, linear + McCormick for q

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Motivation and contributions

MILP approximation of AC power flow equations

Integer L-shaped method for power ▷ system restoration

Numerical results

Conclusions and future work

Integer L-shaped method for power system restoration

Optimal power system restoration

- □ Objective: return the system to **normal operation**
- □ Critical loads must be energized, **normal load is a tool**

$$\max \sum_{t} \left(\text{inertia}(t) + \# \text{ branches energized}(t) \right)$$

s.t. generators: off, cranking, normal operation
branches: can be energized at t only if a terminal is energized on t - 1
buses: can be energized only if connected to energized line or generator*
grid: must be AC feasible for all t

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Integer L-shaped algorithm

- □ Idea: exploit procedure followed by operators
- □ Master problem: energization decisions for all components (ILP)
- \Box Slave problem: AC feasibility for all t (NLP, approximated by MILP)
- 1. Start solving integer master
- 2. Whenever a **new incumbent** of the *master* is found:
 - (a) Detect islands (connected components) of the grid for all t
 - (b) Check feasibility of **each island** (highly parallelizable)
 - (c) Add island feasibility cuts to *master*
- 3. Return to 2.

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 \Box Islands are specified by:

- Subset of buses, N_i
- Non-energized/energized branches connected buses in N_i , L_i^{OFF}/L_i^{ON}
- Non-energized/cranking/energized generators connected to buses in N_i , $G_i^{OFF}/G_i^{CRANK}/G_i^{ON}$
- □ No-good island cut (if island is infeasible)

$$\sum_{l \in L_i^{OFF}} u_l + \sum_{l \in L_i^{ON}} (1 - u_l) + \sum_{g \in G_i^{OFF}} u_g + \dots \ge 1$$

□ Feasibility cuts can be shared across all periods, limited to a window for practical performance

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Hybrid Benders-no-good island cuts

- □ Solving convex relaxation of MILP approximation, similar to LP approximation (Coffrin and Van Hentenryck, 2014)
- $\hfill\square$ If convex relaxation is infeasible, the following cut is valid

$$V + \sum_{g \in G_i} (W_g u_g + X_g v_g) \le M \cdot \left(\sum_{l \in L_i^{OFF}} u_l + \sum_{l \in L_i^{ON}} (1 - u_l) \right)$$

where V, W, X describe an unbounded ray of the dual of the underlying convex relaxation and M is computed for each cut

- Prevents arbitrarily large parameters (transmission switching) from affecting cuts
- □ Using locally ideal formulation for MILP approximation (Sridhar *et* al., 2013) \rightarrow convex relaxation corresponds to LP relaxation

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Numerical results

Test instances.

Name	# buses	# branches	# shunts	# gens	# loads	T
IEEE-39*	39	46	0	10	21	50
IEEE-118*	118	186	14	55	99	50
Chilean SIC	1548	1954	159	297	605	100

- Implemented using Julia, JuMP, LightGraphs (island detection), Ipopt (approximation) and Cplex (LP/MILP solves)
- □ Solving restoration with DC oracle (DC), convex relaxation of MILP AC approximation (Cvx AC) and MILP AC approximation^{*} (AC)
- □ Each experiment ran on single node of cab cluster: 16 cores, 32 GB of memory (no parallelization at this point)
- □ Lazy piece-wise modelling of AC power flow with up to 4 pieces, cut window: 1 period backward, 5 periods forward

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Performance on IEEE-39

 $\hfill\square$ Identical optimal restoration plan for DC, Cvx AC and AC

- $P_q^{\min} = 0 \quad \forall g \rightarrow \text{generators can be turned on without load}$
- Short lines (small shunt capacitances) \rightarrow no need for picking up load
- □ Optimal plan is **first incumbent** of the *master* (no cuts added), solved in 8.5 (DC) 16.6 (AC) secs



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Performance on IEEE-118

- \Box Identical optimal plans for *DC* and *Cvx AC*, different for *AC*
- □ Solved in 10.3 secs for *DC*, 15.8 secs for *Cvx AC* and **772.5** secs for *AC*
- □ AC feasibility **delays energization** of several branches because of **excess of reactive power**

Snapthots of AC restoration plan



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- □ Slightly different optimal restoration plans for DC and Cvx AC, while AC runs out of time (16hrs)
- □ Hundreds to thousands of cuts applied to the *master*, solved in 707.1 secs (DC) and 838.2 secs (Cvx AC)



Cvx AC restoration plan at t = 5

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- □ Slightly different optimal restoration plans for DC and Cvx AC, while AC runs out of time (16hrs)
- □ Hundreds to thousands of cuts applied to the *master*, solved in 707.1 secs (DC) and 838.2 secs (Cvx AC)



Cvx AC restoration plan at t = 7

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- □ Slightly different optimal restoration plans for DC and Cvx AC, while AC runs out of time (16hrs)
- □ Hundreds to thousands of cuts applied to the *master*, solved in 707.1 secs (DC) and 838.2 secs (Cvx AC)



Cvx AC restoration plan at t = 9

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- □ Slightly different optimal restoration plans for DC and Cvx AC, while AC runs out of time (16hrs)
- □ Hundreds to thousands of cuts applied to the *master*, solved in 707.1 secs (DC) and 838.2 secs (Cvx AC)



Cvx AC restoration plan at t = 11

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Conclusions

- □ Convex relaxations of AC power flow fail in situations of excess of reactive power
- □ Hybrid cuts: stronger than no-good cuts and (likely) to be applicable in other contexts
- □ L-shaped approach allows to solve systems **one order of magnitude larger** than state-of-the-art using convex relaxation

Future extensions

- \Box Parallelization of feasibility check expected speedups of 20-50
- □ Speeding-up solution of AC MILP feasibility check
- □ Primal heuristics: rolling horizon and convex relaxation
- □ Solving (stochastic) optimal black-start allocation, optimal islanding and green power system planning

Thank you

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