

Stochastic Programming for Improved Electricity Market Operations with Renewable Energy

Canan Uckun,¹ Audun Botterud,¹ John R. Birge²

¹Argonne National Laboratory

²The University of Chicago

cuckun@anl.gov, abotterud@anl.gov, john.birge@chicagobooth.edu

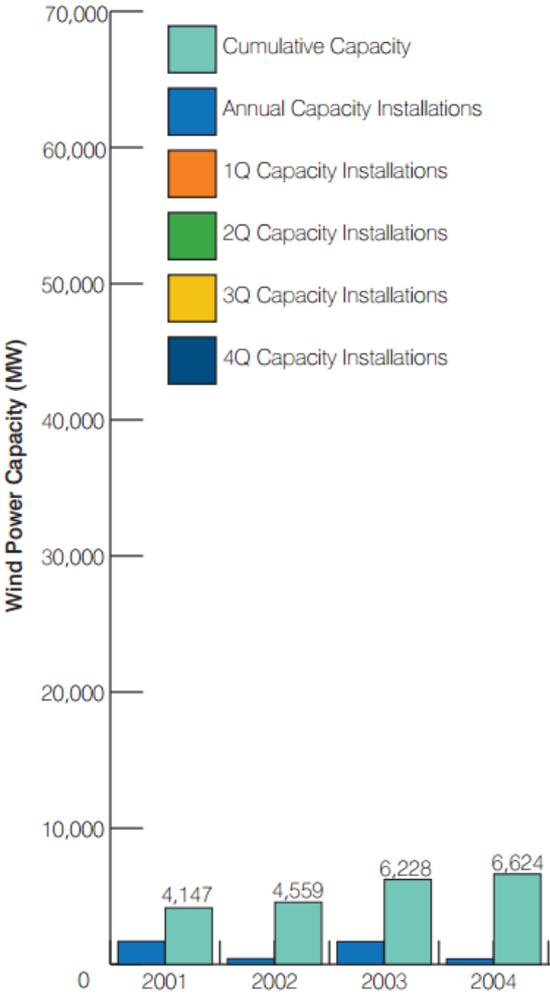
Federal Energy Regulatory Commission, Washington DC, June 25 2013

Outline

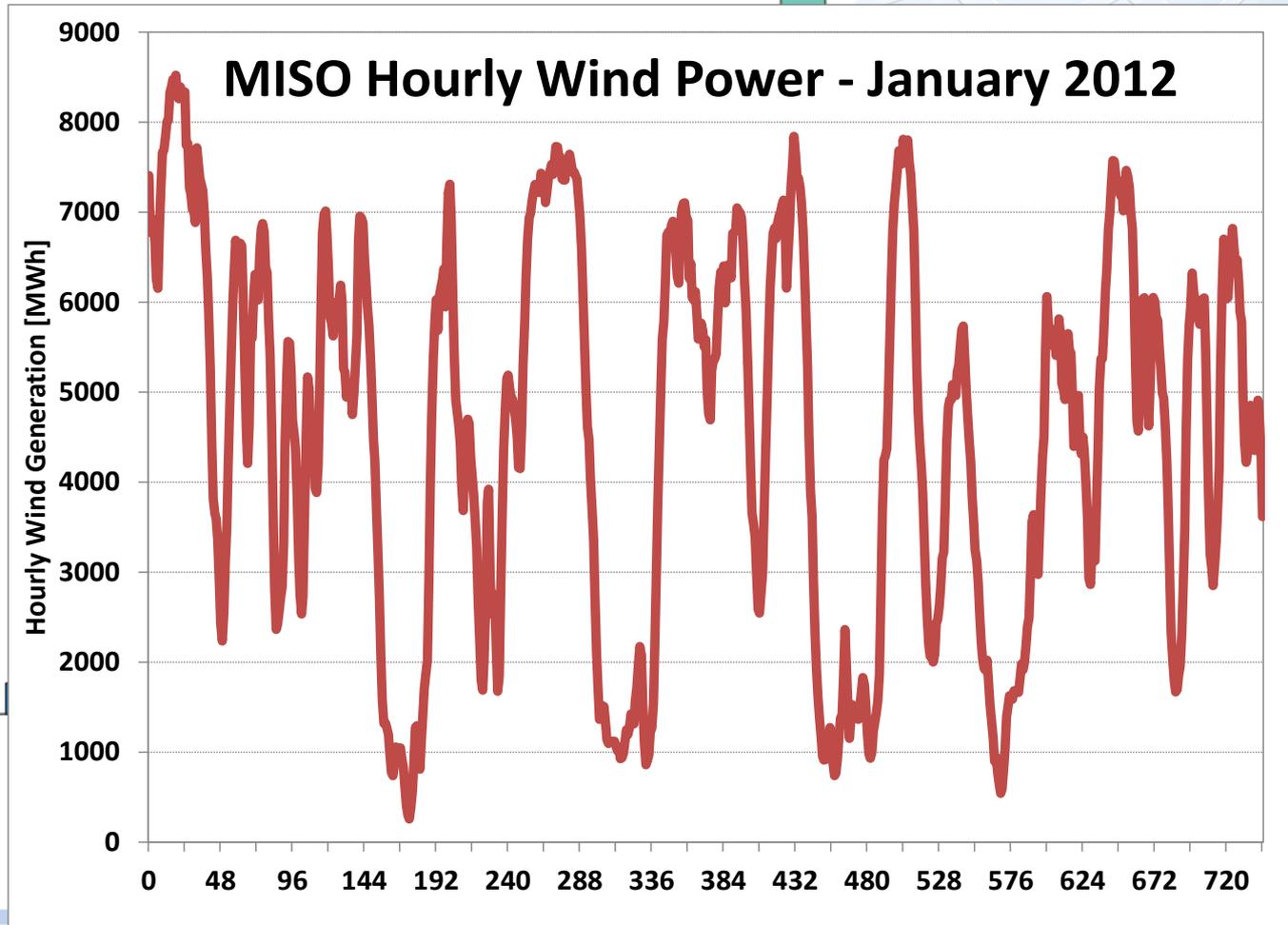
- Introduction
 - Renewable energy in the United States
 - Stochastic Programming
- Scenario generation and reduction
 - Scenarios from probabilistic wind power forecasts
 - Implications for stochastic unit commitment problem
- Stochastic unit commitment experiments
 - Basic model formulation
 - Scenario bundling and non-anticipativity
 - Alternative model formulation with bundles
 - Illustrative examples
- Concluding Remarks



U.S. Wind Power Capacity Reaches 60 GW (282 GW Globally)



60,007

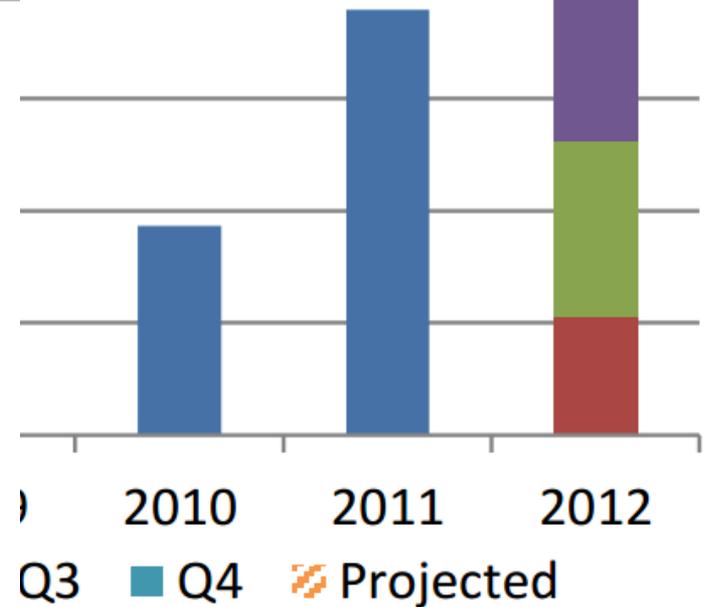
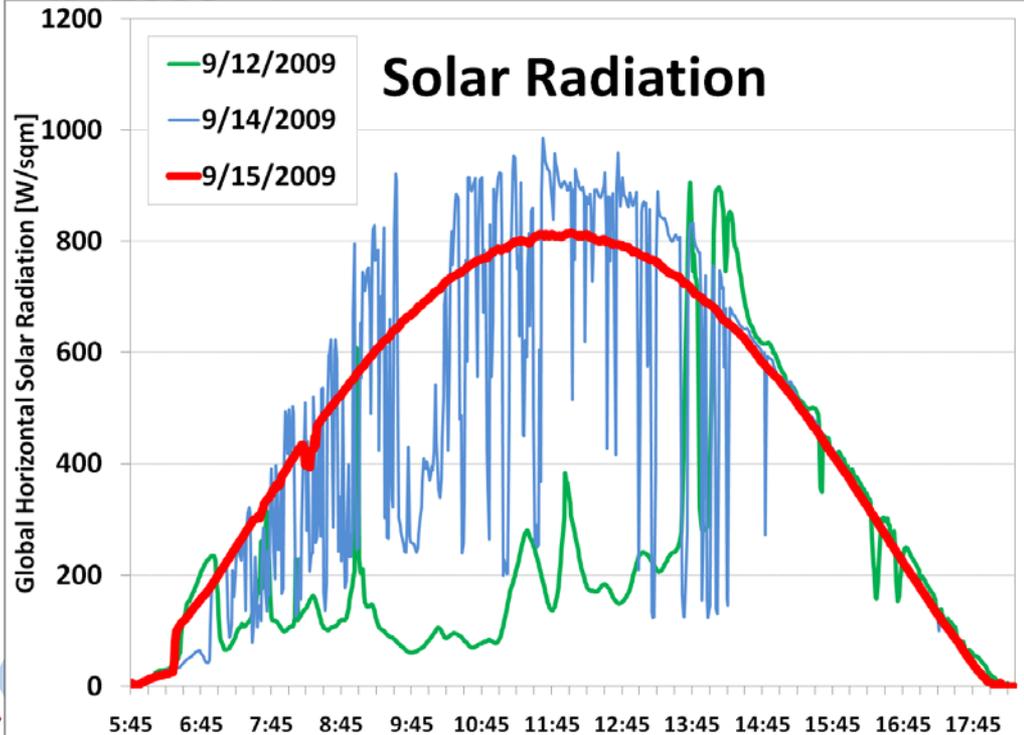
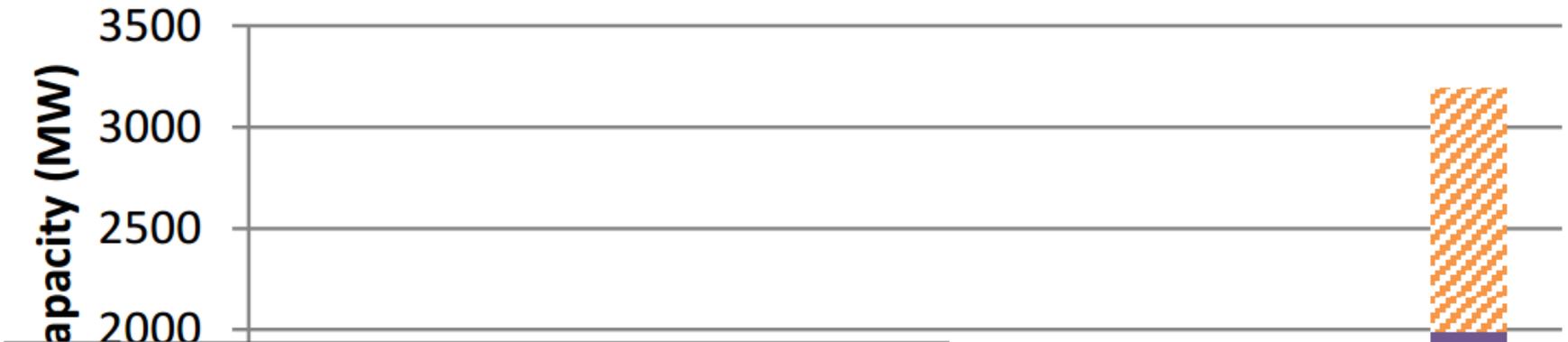


Source: AWEA, 2013 MISO 2012



U.S. Solar PV Capacity Reaches 6.4 GW (over 100 GW Globally)

New U.S. Solar Electric Installations



Source: SEIA 2012

Why Stochastic Programming?

- Weather-driven renewables are hard to forecast and increase the uncertainty in the electric power grid
- Stochastic programming could serve as a tool to address the increased uncertainty in power system and electricity market operations
- Stochastic programming is a powerful tool in dealing with uncertainty, but it has advantages and disadvantages
 - +
 - is based on axioms of foundational decision theory
 - considers uncertainty holistically rather than focusing on worst case scenarios
 - can effectively hedge against randomness
 - - requires probabilistic inputs which may be hard to obtain or estimate
 - can be computationally hard to solve stochastic programming models



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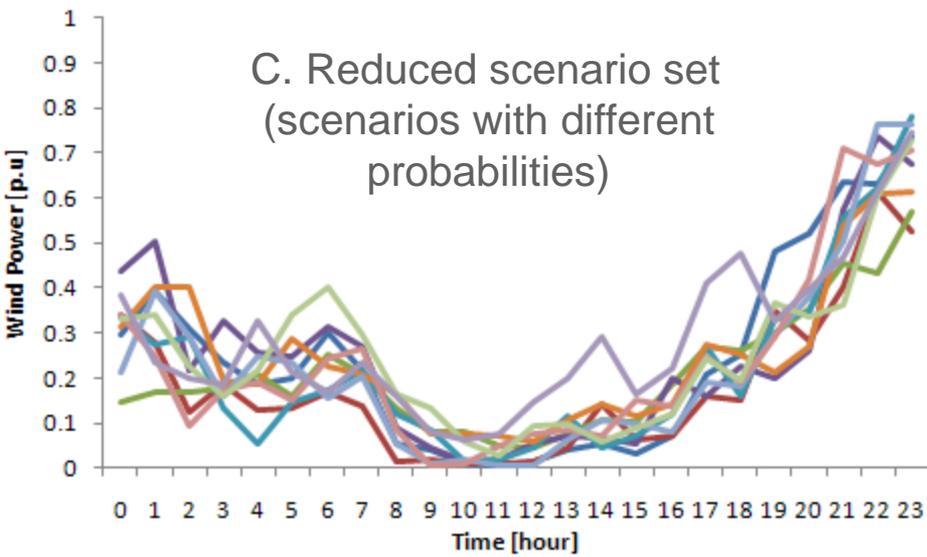
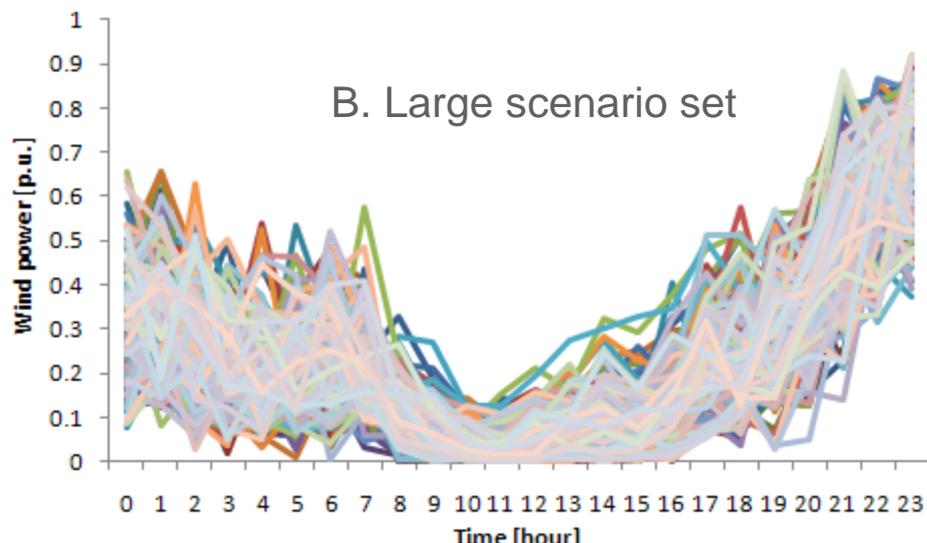
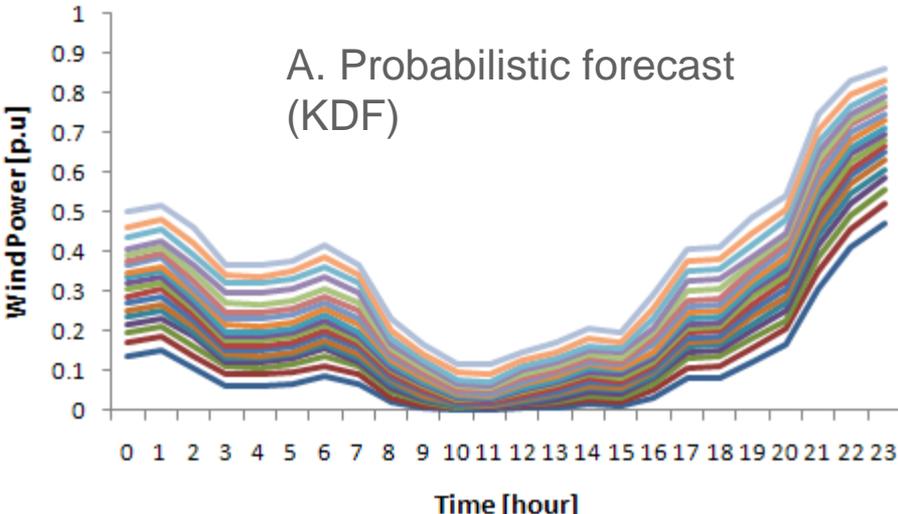


Background: Scenario Generation and Reduction

- We use statistical methods to produce probability density functions for the wind power forecast
 - Kernel Density Forecasting (KDF) [Bessa et al. 2012]
- Stochastic unit commitment model requires scenario representation of wind power forecast → **account for the temporal correlation of forecast errors**
 - A large number of scenarios generated with Monte-Carlo simulation based on quantile distribution (multivariate Gaussian error variable, covariance matrix) [Pinson et al. 09]
- In previous work, we investigated three scenario reduction methods [Botterud et al. 2011]
 - SR1: Random selection
 - SR2: SCENRED in GAMS [Gröwe-Kuska, Heitsch, et. al, 2003]
 - SR3: Scenario clustering approach [Sumaili et al. 2011]

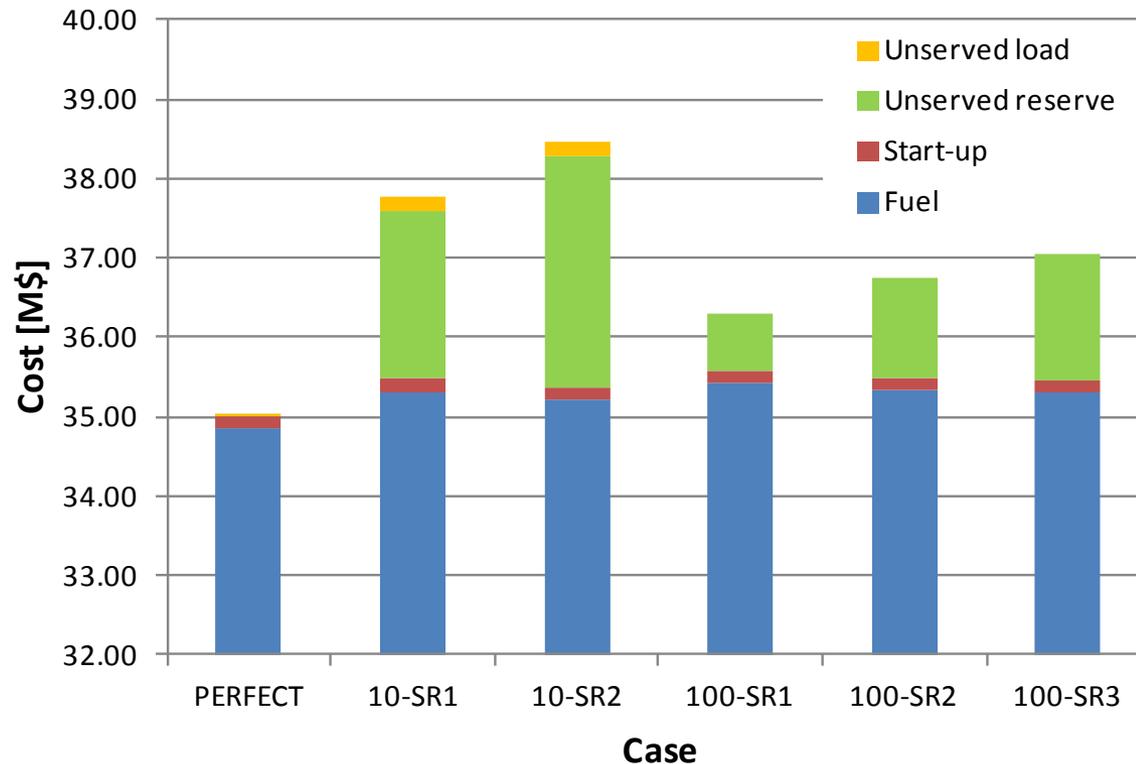


Scenario Generation and Reduction - Illustration



Scenario Selection is Important for Stochastic UC

Total operating costs from “out-of-sample” simulations:



SR1 - Random selection
SR2 - SCENRED (GAMS)
SR3 - Scenario clustering

- Random scenario selection performs better than both scenario reduction algorithms
 - Scenario reduction reduces scenario variance and level of hedging in UC strategy
- Increasing the number of scenarios improves performance
 - Computational burden also increases, 15-20 times longer run-time with 100 scenarios

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Basic UC Model Formulation

Probability of scenario s

Start-up cost

2-Stage Stoch. Prog.:

$$\min \sum_{s \in S} p_s \sum_{i \in I} \sum_{t=1}^T \{g_i(x_{it}^s)u_{it}^s + h_i(u_{i,t-1}^s, u_{it}^s)\}$$

Production cost

subject to:

$\sum_{l \in L_n^{in}} f_{lt}^s + \sum_{i \in I_n} x_{it}^s + \sum_{j \in J_n} w_{jt}^s = \sum_{l \in L_n^{out}} f_{lt}^s + D_t$	$\forall t, s$	Load balance
$f_{lt}^s = B_l(\theta_{nt}^s - \theta_{mt}^s)$	$\forall l = (m, n) \in L, t, s$	Flow computation
$-F_l \leq f_{lt}^s \leq F_l$	$\forall l, t, s$	Flow limits
$w_{jt}^s \leq W_{jt}^s$	$\forall j, t, s$	Wind curtailment
$\sum_{i=1}^I r_{it}^s \geq R_t$	$\forall t, s$	Spinning reserve requirement
$x_{it}^s + r_{it}^s \leq Q_i u_{it}^{s,b}$	$\forall i, t, s$	Maximum output
$x_{it}^s \leq q_i u_{it}^{s,b}$	$\forall i, t, s$	Minimum output
$x_{it}^s - x_{i,t-1}^s + r_{it}^s \leq u_{i,t-1}^{s,b} \Delta_i + (1 - u_{i,t-1}^{s,b}) \Delta_i^{SU}$	$\forall i, t \geq 2, s$	Ramp-up/Start-up
$x_{i,t-1}^s - x_{it}^s \leq u_{it}^{s,b} \Delta_i + (1 - u_{it}^{s,b}) \Delta_i^{SD}$	$\forall i, t \geq 2, s$	Ramp-down/Shutdown
$u_{it}^{s,b} - u_{i,t-1}^{s,b} \leq u_{it}^{s,b}$	$\forall t \geq 2, s, \tau = t + 1, \dots, \min\{t + L_i - 1, T\}$	Minimum up-time
$u_{i,t-1}^{s,b} - u_{it}^{s,b} \leq 1 - u_{it}^{s,b}$	$\forall t \geq 2, s, \tau = t + 1, \dots, \min\{t + l_i - 1, T\}$	Minimum down-time
$u_{it}^s = u_{it}$	$\forall t, i, s$	Non-anticipativity
$x_{it}^s, r_{it}^s \geq 0$	$\forall t, i, s$	Non-negativity
$w_{jt}^s \geq 0$	$\forall t, j, s$	Non-negativity
$u_{it}^s, u_{it} \in \{0, 1\}$	$\forall t, i, s$	Integrality

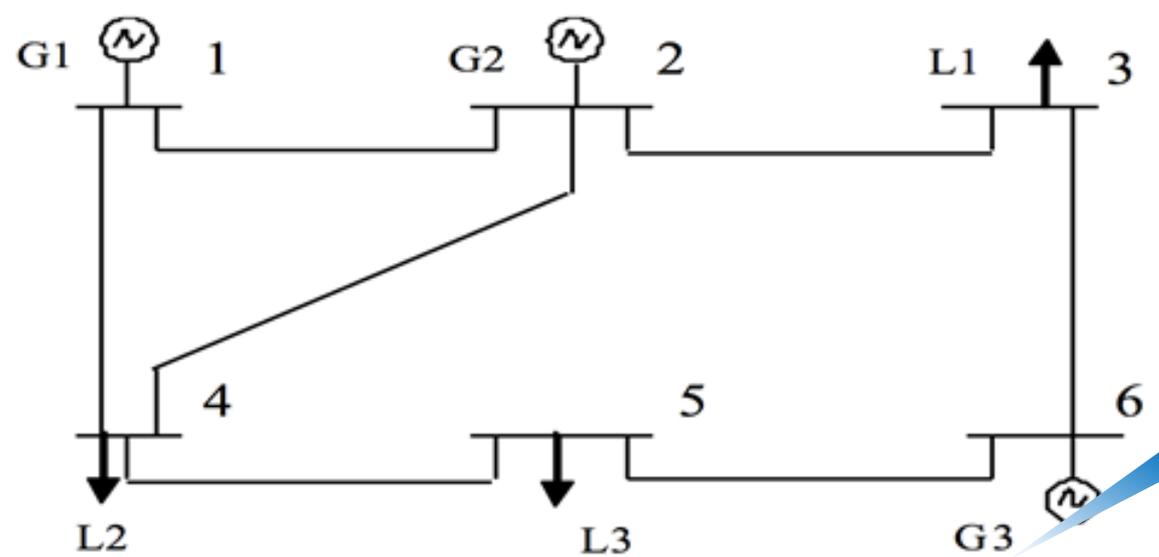


We use Sandia National Laboratories' optimization tool Coopr, in particular ***PySP (Python-based Stochastic Programming)*** modeling and solver library (Watson et al. 2012). The tool can solve the problem in two ways:

- Extensive form
- Progressive Hedging
 - ***Scenario-based decomposition scheme***
 - ***Relaxation of non-anticipativity constraints***
 - ***Has been used for unit commitment (e.g. Takriti et al. 1996)***



Illustrative 6-Bus System



Replaced with a wind unit

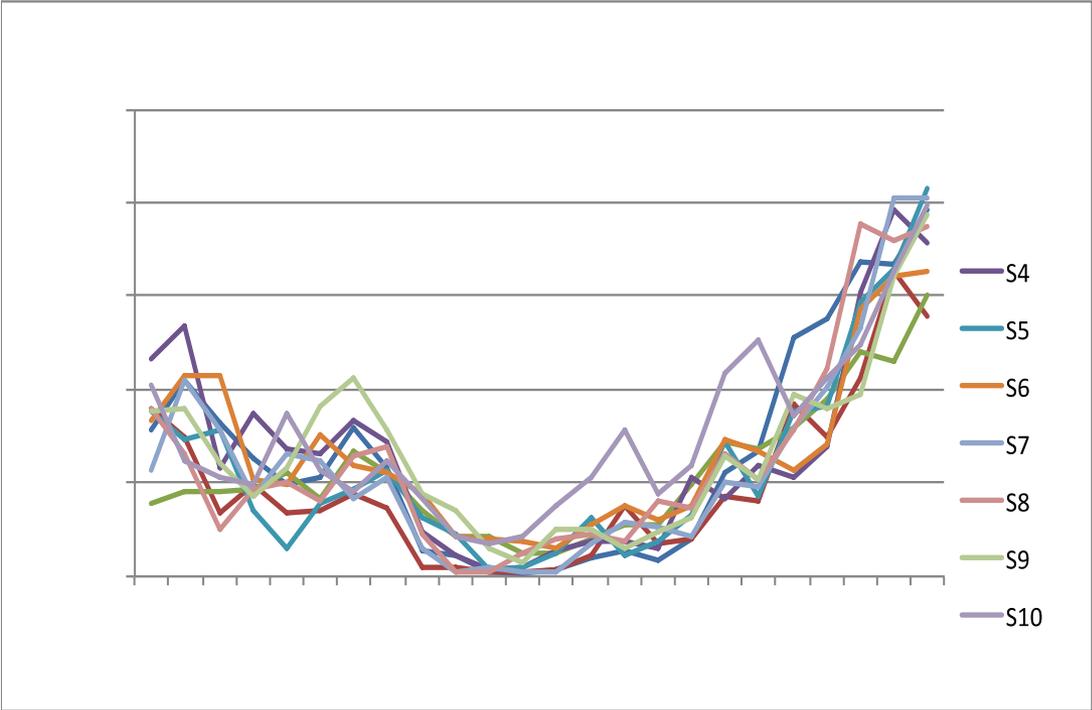
- 6-Bus system* with
- 2 thermal generators
 - 3 loads

	Bus No.	Unit Cost Coefficients			Pmax (MW)	Pmin (MW)	Ini. State (h)	Min Off (h)	Min On (h)	Ramp (MW/h)	Start Up (MBtu)	Fuel Price (\$/MBtu)
		U	b (MBtu/MW)	c (MBtu/MW ²)								
G1	1	176.95	13.51	0.0004	220	100	4	4	4	55	10	1
G2	2	129.98	32.63	0.001	100	10	3	3	2	50	200	1

* The details of the system and parameters are available at: <http://motor.ece.iit.edu/data/>



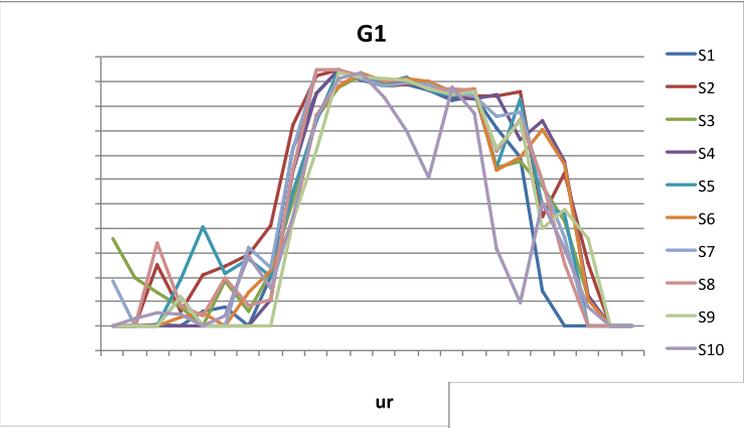
Wind Power Day-Ahead Forecast Scenarios



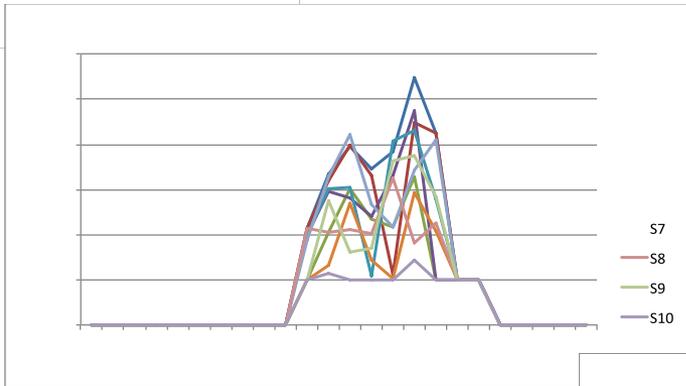
- 10 wind scenarios
- Derived from EWITS data with KDF, MC sampling, and scenario reduction
- Wind unit capacity is set so that it can satisfy 30% of the daily load



Basic UC Model: Dispatch Results

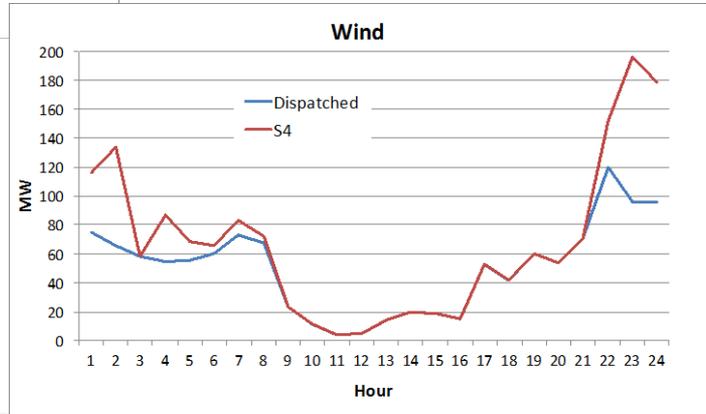


Unit 1 is always on.



Unit 2 is on when the wind generation is low.

Wind is dispatched down (curtailed) early morning and late night.



The Expected Value of Perfect Information (EVPI)

	Probability	Total cost (\$)
Scenario 1	0.10	61,306
Scenario 2	0.06	64,503
Scenario 3	0.09	59,321
Scenario 4	0.07	61,067
Scenario 5	0.11	61,996
Scenario 6	0.19	58,074
Scenario 7	0.13	61,944
Scenario 8	0.10	59,577
Scenario 9	0.08	58,850
Scenario 10	0.07	53,268
Perfect information solution		59,913
Stochastic solution		60,427
<i>The expected value of perfect information (EVPI)</i>		515



The Value of a Stochastic Solution (VSS)

	Load Curtailment	Total cost (\$)
Scenario 1	0.00	61,306
Scenario 2	3.90	77,523
Scenario 3	0.00	59,321
Scenario 4	1.72	66,755
Scenario 5	0.46	62,950
Scenario 6	0.00	58,074
Scenario 7	0.00	61,944
Scenario 8	0.00	59,577
Scenario 9	0.00	58,850
Scenario 10	0.00	53,526
Expected value solution		61,247
Stochastic solution		60,427
<i>The value of stochastic solution (VSS)</i>		880



Alternative Approach with Bundling of Scenarios

- Stochastic programming models tend to give better results with more scenarios, capturing the full range of uncertainty.
- Unit commitment is a multi-stage decision problem in electricity market operations (day-ahead, reliability, real-time).
- To solve the problem with a large number of scenarios and to capture the multi-stage decision process we consider bundling. We observe that:
 - the scenarios can be bundled according to their deviation from the average forecast.
 - the bundles might be different across the time horizon.
- The idea is:
 - to enforce the non-anticipativity constraints for the bundles only



Alternative Model Formulation with Bundles

Add bundle indices to the unit commitment decision

$$\min \sum_{s \in S} p_s \sum_{i \in I} \sum_{t=1}^T \{g_i(x_{it}^s) u_{it}^{s,b} + h_i(u_{i,t-1}^{s,b}, u_{it}^{s,b})\}$$

subject to:

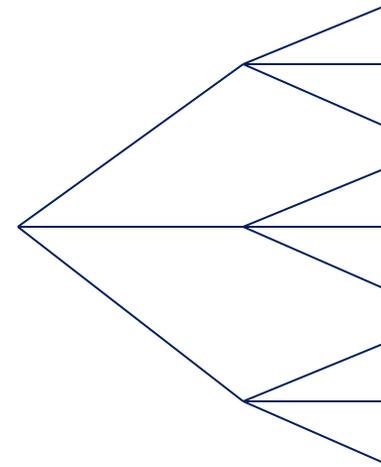
$\sum_{l \in L_n^{in}} f_{lt}^s + \sum_{i \in I_n} x_{it}^s + \sum_{j \in J_n} w_{jt}^s = \sum_{l \in L_n^{out}} f_{lt}^s + D_t$	$\forall t, s$	Load balance
$f_{lt}^s = B_l(\theta_{nt}^s - \theta_{mt}^s)$	$\forall l = (m, n) \in L, t, s$	Flow computation
$-F_l \leq f_{lt}^s \leq F_l$		
$w_{jt}^s \leq W_{jt}^s$		
$\sum_{i=1}^I r_{it}^s \geq R_t$		
$x_{it}^s + r_{it}^s \leq Q$		
$x_{it}^s \leq q_i u_{it}^{s,b}$		
$x_{it}^s - x_{i,t-1}^s$		
$x_{i,t-1}^s - x_{it}^s \leq u_{it}^{s,b} \Delta_i + (1 - u_{it}^{s,b}) \Delta_i^{SD}$	$\forall i, t \geq 2, s$	Ramp-down/Shutdown
$u_{it}^{s,b} - u_{i,t-1}^{s,b} \leq u_{it}^{s,b}$	$\forall t \geq 2, s, \tau = t + 1, \dots, \min\{t + L_i - 1, T\}$	Minimum up-time
$u_{i,t-1}^{s,b} - u_{it}^{s,b} \leq 1 - u_{it}^{s,b}$	$\forall t \geq 2, s, \tau = t + 1, \dots, \min\{t + l_i - 1, T\}$	Minimum down-time
$u_{it}^{s,b} = u_{it}^b$	$\forall t, i, s$	Non-anticipativity
$x_{it}^s, r_{it}^s \geq 0$	$\forall t, i, s$	Non-negativity
$w_{jt}^s \geq 0$	$\forall t, j, s$	Non-negativity
$u_{it}^s, u_{it} \in \{0,1\}$	$\forall t, i, s$	Integrality

What if we divide the time horizon into time blocks, and enforce the non-anticipativity constraints across bundles only?
 → If the scenarios in the bundles behave similarly, we could get the same solution with LESS non-anticipativity constraints by enforcing them at the end of the blocks only.



Bundling Approach

- Tradeoff
 - More variables versus ability to capture uncertainty
- Advantages of bundling
 - Captures multi-stage decision process
 - no need to enforce formal tree structure
 - Reduces the need for scenario reduction
 - can take into account extreme scenarios
 - May reduce computational burden
 - relaxation of traditional 2-stage formulation
- Three approaches
 - Non-anticipativity constraints across scenarios
 - Non-anticipativity constraints across bundles
 - Non-anticipativity constraints across bundles at the end of the blocks

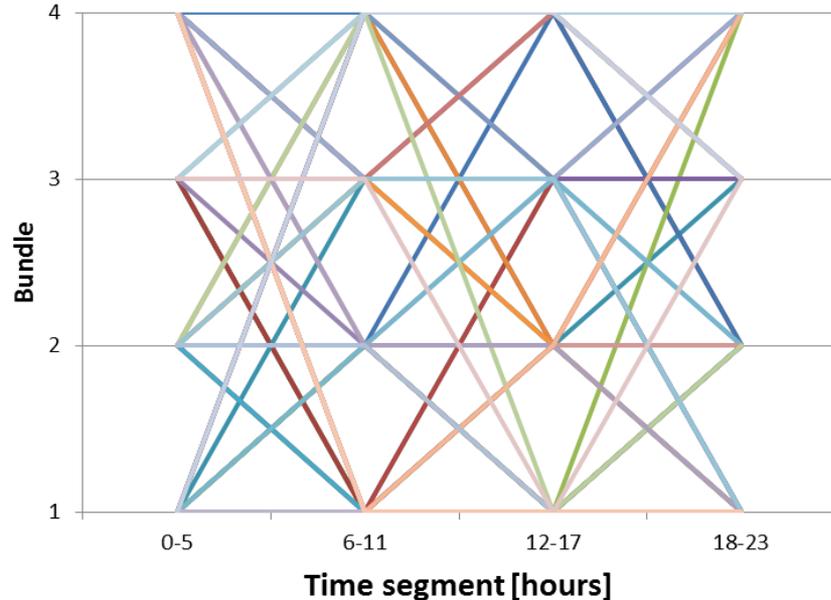
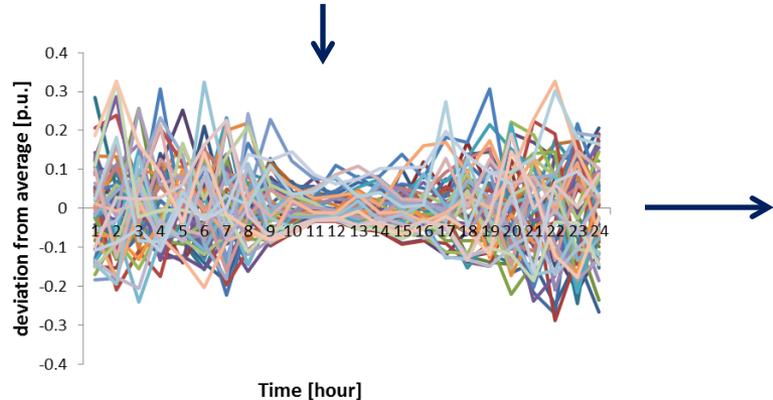
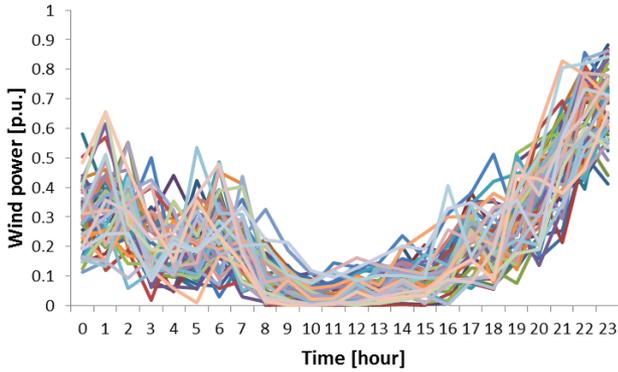


Bundles for 50 Scenarios (Day-Ahead Forecast)

Bundling

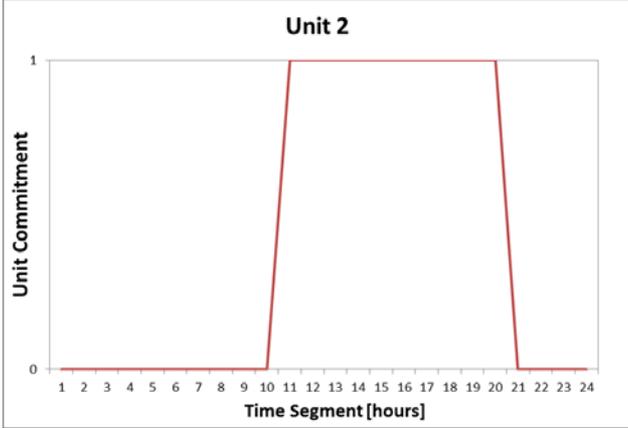
– According to the deviations from the average forecast

- < 25% quantile -> Bundle 1
- < 50% quantile -> Bundle 2
- < 75% quantile -> Bundle 3
- < 100% quantile -> Bundle 4

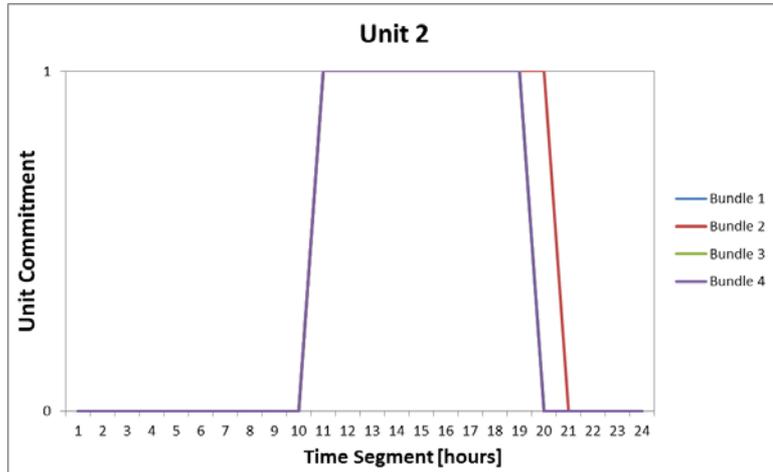


Bundle UC Model: Dispatch Result Comparison

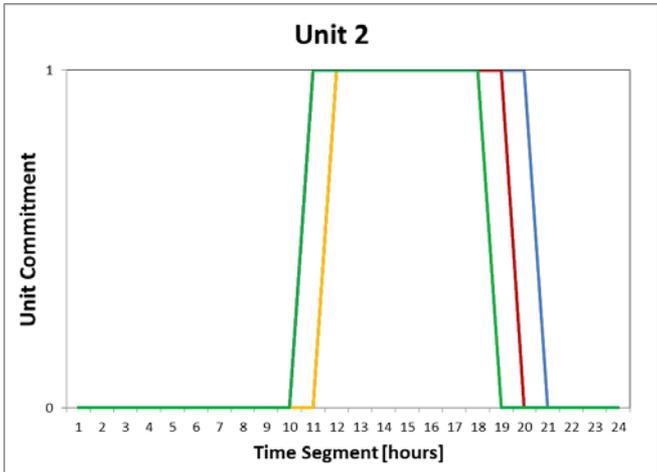
- Unit 1 is always on for the three approaches.
- Unit 2 decision may change depending on the scenario.



“Across all scenarios”



“Across bundles”



“Across bundles at the end of time blocks”



Bundle UC Model: Objective Function and Run-time

Extensive Form	“Across scenarios”	“Across bundles”	“Across bundles at the end of time blocks”
Objective	62,401	62,162	61,860
Execution time (sec)	18.15	23.37	23.29

Progressive Hedging*	“Across scenarios”	“Across bundles”	“Across bundles at the end of time blocks”
Objective	62,401	62,162	61,846
Execution time (sec)	635.29	400.56	399.19
Number of PH iterations	50	26	29

The bundling approach gives

*rho = 200

- Lower expected operating cost
- Improved run-time and fewer iterations (under PH)



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Conclusions and Future Work

- Stochastic programming is a powerful tool in solving problems with uncertainty
 - Has the potential to address uncertainty from renewables in operational decisions
- Computational effort is a challenge
 - We propose addressing this by bundling forecast scenarios and reducing the number of non-anticipativity constraints within a progressive hedging framework
 - The formulation also captures some of the multi-stage nature of the unit commitment problem
- Future work includes
 - Developing methods for more effective bundling of scenarios
 - Solving larger problems with more scenarios and stochastic variables
 - Investigate potential for improved pricing and financial incentives under stochastic scheduling



References and Acknowledgement

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