

Minimizing load shedding in electricity networks by preventive islanding

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FERC
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Background

Project structure

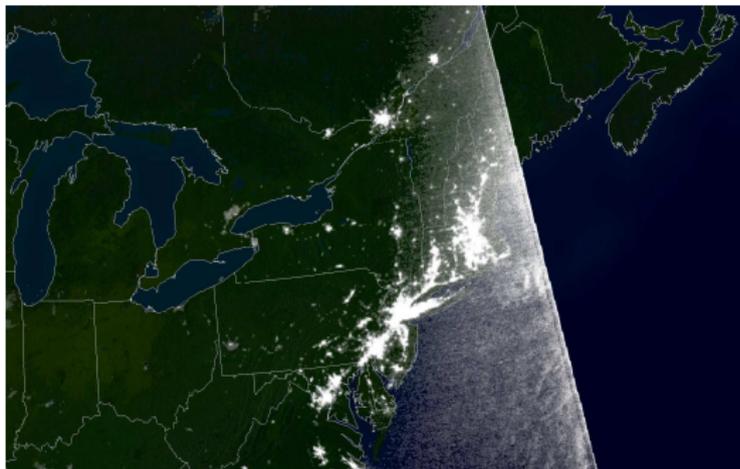
- ▶ EPSRC funded project led by **Janusz Bialek** at Durham University with groups at Edinburgh and Southampton.

Group Responsibilities:

- ▶ Durham: Electrical Engineering: **System dynamics**
- ▶ Southampton: Mathematics: **Laplacian based graph partitioning**
- ▶ Edinburgh: OR and Optimization: **Steady state optimization**

USA Aug 2003

Happy customers

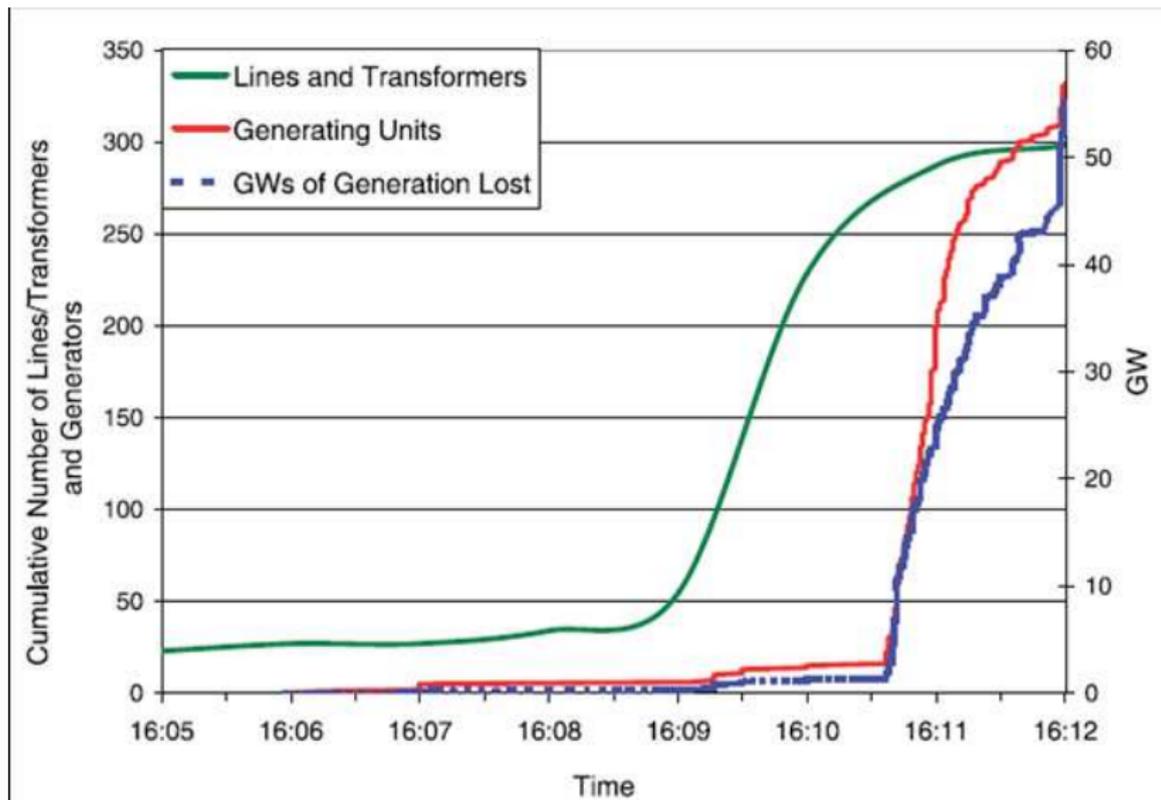


Oooops !

There goes
Long Island,
Detroit,
Ottawa,
Toronto ...



USA Aug 2003



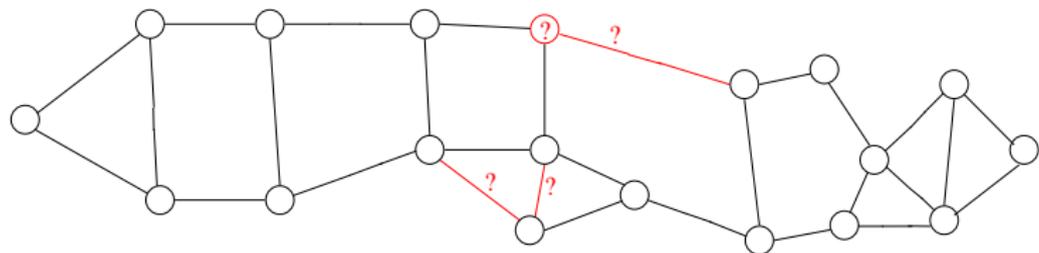
Background

Goal

- ▶ Develop a tool that can create a *Firewall* to isolate the troubled area from the rest of the network.
- ▶ Leave network in a stable steady state.
- ▶ Could be used for off line analysis to prepare responses to faults in different areas or, if fast enough, to react in real time.

Sectioning “uncertain” parts of network

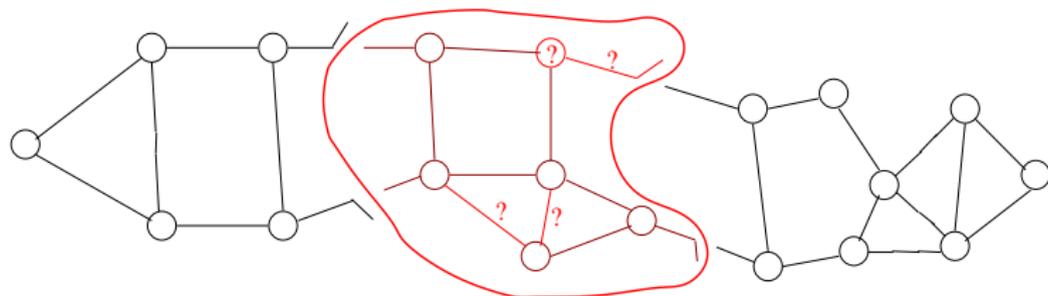
- ▶ Network has “uncertain” buses/lines/generators ? ? ?



Sectioning “uncertain” parts of network

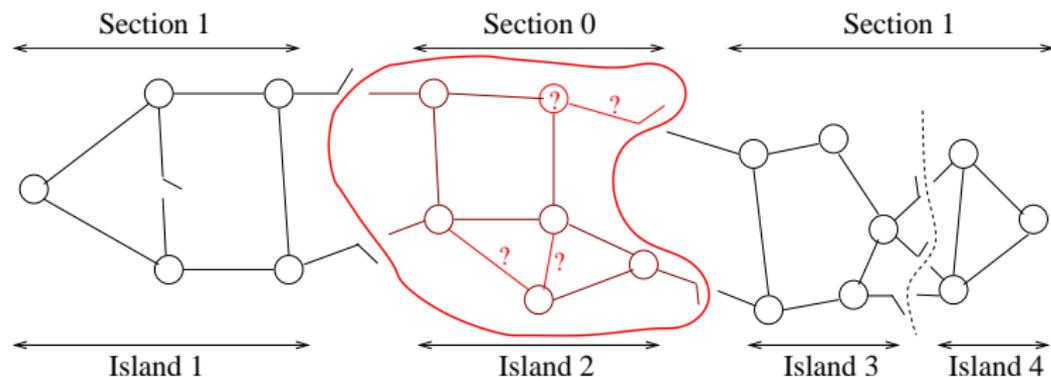
Form a Firewall

- ▶ to: Achieve a new “safe” steady state that isolates all “uncertain” buses/lines/generators
- ▶ by: Cutting lines & Shedding loads & Adjusting generation
- ▶ goal: Minimize the load shed



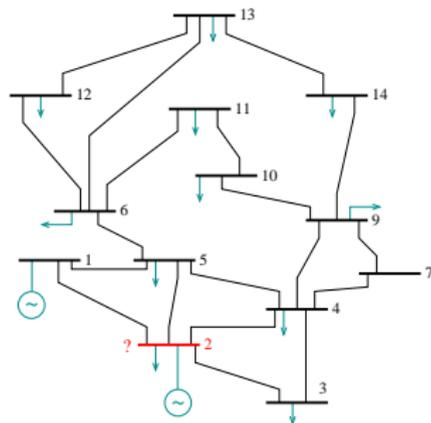
Sectioning “uncertain” parts of network

- ▶ **Section 0** – uncertain parts, **Section 1** – certain parts
- ▶ All load in section 0 is at risk, with chance β of surviving

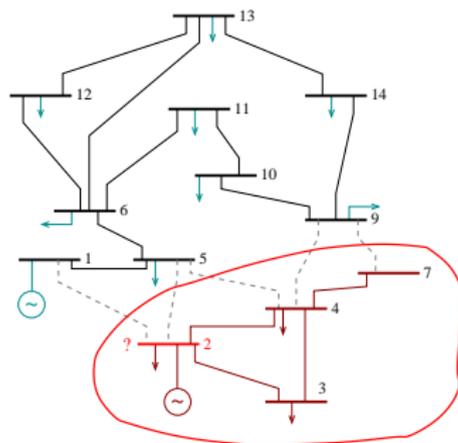


Sectioning with uncertainty: $\beta = 0.5$

Before



After

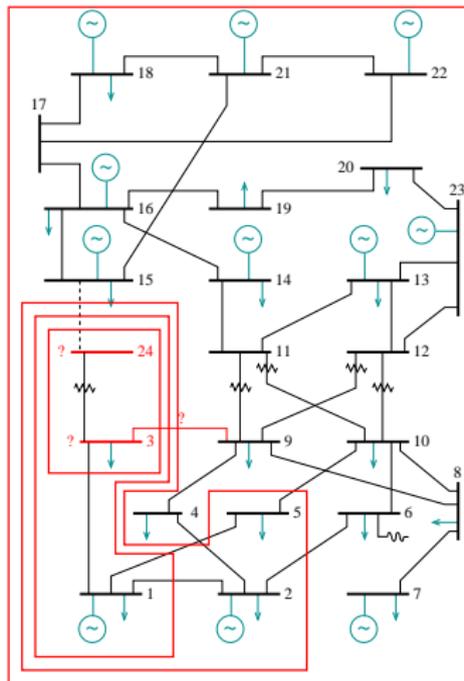


- ▶ 259 MW total load
- ▶ 0.0 MW load shed
- ▶ 129.5 expected loss

- ▶ 0.0 MW shed in Section 1
- ▶ 35.9 MW shed in Section 0
- ▶ 127.8 MW at risk in Section 0
- ▶ 99.8 MW expected loss

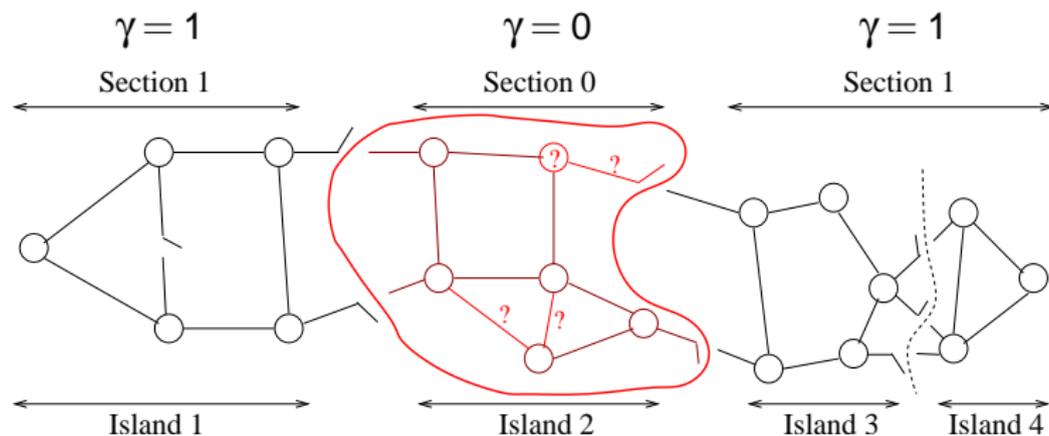
Growth of section 0 in 24 bus network as $\beta \rightarrow 1$

$$0.00 \leq \beta \leq 1.00$$



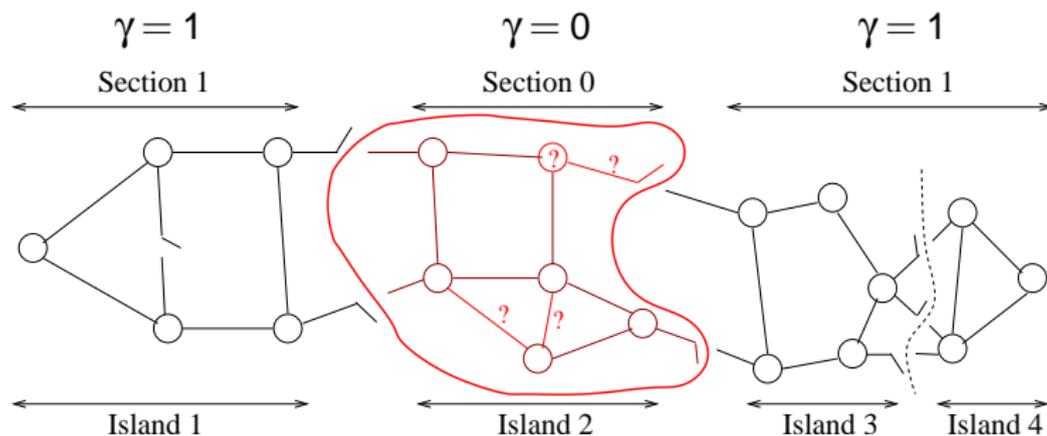
Sectioning Constraints

- ▶ Uncertain buses, \mathcal{B}^0 , and lines, \mathcal{L}^0
- ▶ Optimization decides what else in 0 & 1 and which line to cut
- ▶ $\gamma_b =$ section for bus b
- ▶ $\rho_{bb'} = 0$ if line bb' is cut, and 1 otherwise

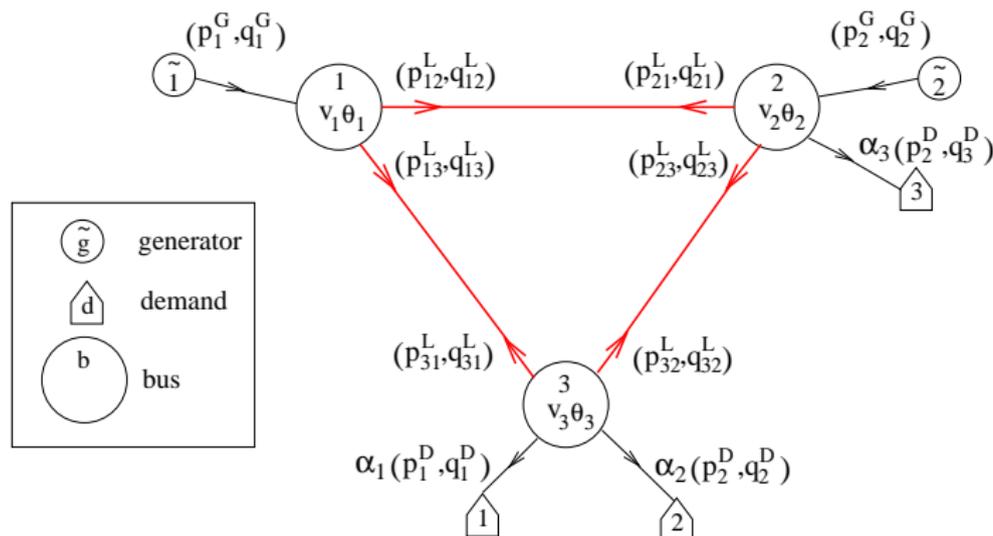


Sectioning Constraints

- $\rho_{bb'} \leq 1 + \gamma_b - \gamma_{b'}$ $bb' \in \mathcal{L} \setminus \mathcal{L}^0$ No lines between sections
 $\rho_{bb'} \leq 1 - \gamma_b + \gamma_{b'}$ $bb' \in \mathcal{L} \setminus \mathcal{L}^0$ No lines between sections
 $\rho_{bb'} \leq 1 - \gamma_b$ $bb' \in \mathcal{L}^0$ No unsafe lines in Section 1
 $\rho_{bb'} \leq 1 - \gamma_{b'}$ $bb' \in \mathcal{L}^0$ No unsafe lines in Section 1
 $\gamma_b = 0$ $b \in \mathcal{B}^0$ All unsafe buses in Section 0

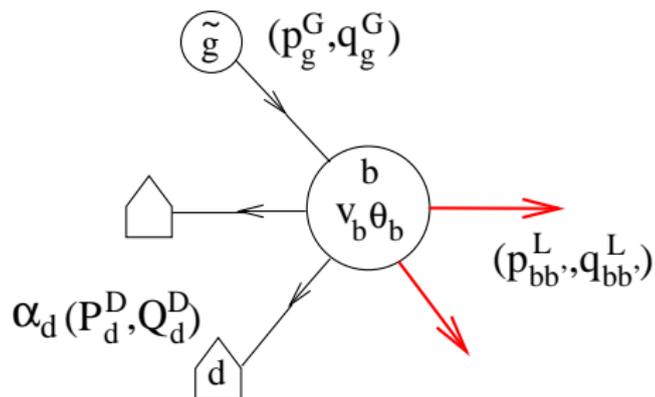


AC power flow model: Notation



- v_b, θ_b voltage and phase angle at bus b
 $p_{bb'}^L, q_{bb'}^L$ real and reactive power flows into line (b, b') from bus b
 p_g^G, q_g^G real and reactive power output of generator g
 P_d^D, Q_d^D real and reactive power demand at load d
 α_d proportion of load d connected — $\alpha_d \in [0, 1]$

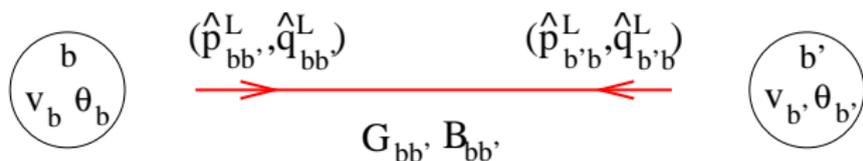
Kirchhoff Current Law (KCL): conservation of flow at buses



$$\sum_{g \in G_b} p_g^G = \sum_{d \in D_b} \alpha_d P_d^D + \sum_{b' \in B_b} p_{bb'}^L \quad \text{Real balance}$$

$$\sum_{g \in G_b} q_g^G = \sum_{d \in D_b} \alpha_d Q_d^D + \sum_{b' \in B_b} q_{bb'}^L \quad \text{Reactive balance}$$

Kirchhoff Voltage Law (KVL): flow-voltage relations on lines



$$\delta_{bb'} = \theta_b - \theta_{b'}$$

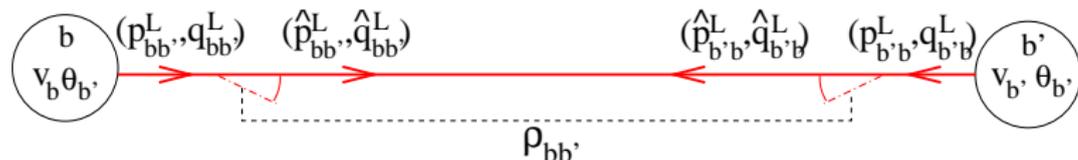
$$\hat{p}_{bb'}^L = G_{bb'} v_b (v_b - v_{b'} \cos \delta_{bb'}) - B_{bb'} v_b v_{b'} \sin \delta_{bb'}$$

$$\hat{q}_{bb'}^L = B_{bb'} v_b (v_{b'} \cos \delta_{bb'} - v_b) - G_{bb'} v_b v_{b'} \sin \delta_{bb'} - v_b^2 C_{bb'}$$

- Because of power losses in the lines

$$\hat{p}_{bb'}^L \neq -\hat{p}_{b'b}^L \text{ and } \hat{q}_{bb'}^L \neq -\hat{q}_{b'b}^L.$$

Disconnecting lines ($p_{bb'}^L$ case)



When $\rho_{bb'} = 0$, line is not connected, so $p_{bb'}^L = 0$

When $\rho_{bb'} = 1$, line is connected, so $p_{bb'}^L = \hat{p}_{bb'}^L$

MILP Formulation

$$-\rho_{bb'} P_{bb'}^{L\max} \leq p_{bb'}^L \leq P_{bb'}^{L\max} \rho_{bb'},$$

$$-(1 - \rho_{bb'}) \hat{P}_{bb'}^{L\max} \leq \hat{p}_{bb'}^L - p_{bb'}^L \leq \hat{P}_{bb'}^{L\max} (1 - \rho_{bb'}).$$

$P_{bb'}^{L\max}$ is the maximum allowed real flow into the line from b

$\hat{P}_{bb'}^{L\max}$ is the maximum possible value of $\hat{p}_{bb'}^L - p_{bb'}^L$

Bounds on variables

$$p_{bb'} + p_{b'b} \leq H_{bb'}$$

Thermal limit on line

$$V_b^- \leq v_b \leq V_b^+$$

Voltage limit at bus e.g. $v_b \in [0.95, 1.05]$

$$Q_g^{G-} \leq q_g^G \leq Q_g^{G+}$$

Reactive Power limits Q_g^{G-}, Q_g^{G+}

independent of current operating point

$$\zeta_g P_g^{G-} \leq p_g^G \leq \zeta_g P_g^{G+}$$

Real Power limits P_g^{G-}, P_g^{G+}

dependent on current operating point

$\zeta_g = 0$ if generator is switched off

$\zeta_g = 1$ if generator remains on

Objective

Definition

- ▶ **Planned supply:** $P_d^D \alpha_d$
- ▶ **Supply probability:** β in Section 0
- ▶ **Objective:** Maximize expected load supplied

Objective:
$$\max \beta \sum_{d \in S^0} P_d^D \alpha_d + \sum_{d \in S^1} P_d^D \alpha_d$$

IP Formulation

- ▶ Split each α_d into α_{0d} for section 0 and α_{1d} for Section 1

$$\alpha_d = \alpha_{0d} + \alpha_{1d}, \quad 0 \leq \alpha_{1d} \leq \gamma_b$$

Objective:
$$\max \sum_d P_d^D (\beta \alpha_{0d} + \alpha_{1d})$$

Variables for average line flow and loss



► Define

$$\rho_{bb'}^{Av} = \frac{\hat{p}_{bb'} - \hat{p}_{b'b}}{2}$$

$$\rho_{bb'}^{Loss} = \hat{p}_{bb'} + \hat{p}_{b'b}$$

$$q_{bb'}^{Av} = \frac{\hat{q}_{bb'} - \hat{q}_{b'b}}{2}$$

$$q_{bb'}^{Loss} = \hat{q}_{bb'} + \hat{q}_{b'b}$$

$$\hat{p}_{bb'} = \rho_{bb'}^{Av} + \frac{\rho_{bb'}^{Loss}}{2}$$

$$\hat{p}_{b'b} = -\rho_{bb'}^{Av} + \frac{\rho_{bb'}^{Loss}}{2}$$

$$\hat{q}_{bb'} = q_{bb'}^{Av} + \frac{q_{bb'}^{Loss}}{2}$$

$$\hat{q}_{b'b} = -q_{bb'}^{Av} + \frac{q_{bb'}^{Loss}}{2}$$

Approximations of Kirchhoff's Laws

We consider 3 approximations to Kirchhoff's Laws

- ▶ “DC” Constant Loss:
 - ▶ Drop the reactive power constraints
 - ▶ Set all voltages to 1
 - ▶ Assume line loss $p_{bb'}^{Loss} =$ its pre-islanding value
- ▶ AC Linear:
 - ▶ Include reactive power constraints
 - ▶ Linearize KVL
- ▶ AC PWL:
 - ▶ Include reactive power constraints
 - ▶ Linearize KVL
 - ▶ Include PWL approximation of cosine terms

Case: $B = 5, G = 1, C = 0.5, |\delta| \leq 57^\circ, 0.95 \leq v \leq 1.05$.

	max	"DC"	AC Lin	AC PWL
$p^{Av} = -B\delta$	2.500	✓	✓	✓
+ $G(v_b - v_{b'})$	0.100		✓	✓
+ $G/2 ((v_b - 1)^2 - (v_{b'} - 1)^2)$	0.001			
+ $B(1 - v_b v_{b'}) \sin \delta$	0.245			
+ $B(\delta - \sin \delta)$	0.103			
<hr/>				
$p^{Loss} = 2G(1 - \cos \delta)$	0.245			✓
+ $G(v_b - v_{b'})^2$	0.001			
+ $2G(v_b v_{b'} - 1)(1 - \cos \delta)$	0.023			
<hr/>				
$q^{Av} = -G\delta$	0.500		✓	✓
- $(B + C)(v_b - v_{b'})$	0.495		✓	✓
- $(B + C)/2 ((v_b - 1)^2 - (v_{b'} - 1)^2)$	0.001			
+ $G(\delta - \sin \delta)$	0.021			
+ $G(1 - v_b v_{b'}) \sin \delta$	0.051			
<hr/>				
$q^{Loss} = -C(v_b - v_{b'} - 1)$	0.550		✓	✓
- $2B(1 - \cos \delta)$	1.224			✓
- $B(v_b - v_{b'})^2$	0.050			
- $C((v_b - 1)^2 + (v_{b'} - 1)^2) +$	0.000			
+ $2B(v_b v_{b'} - 1)(1 - \cos \delta)$	0.125			

Computational tests

Steps

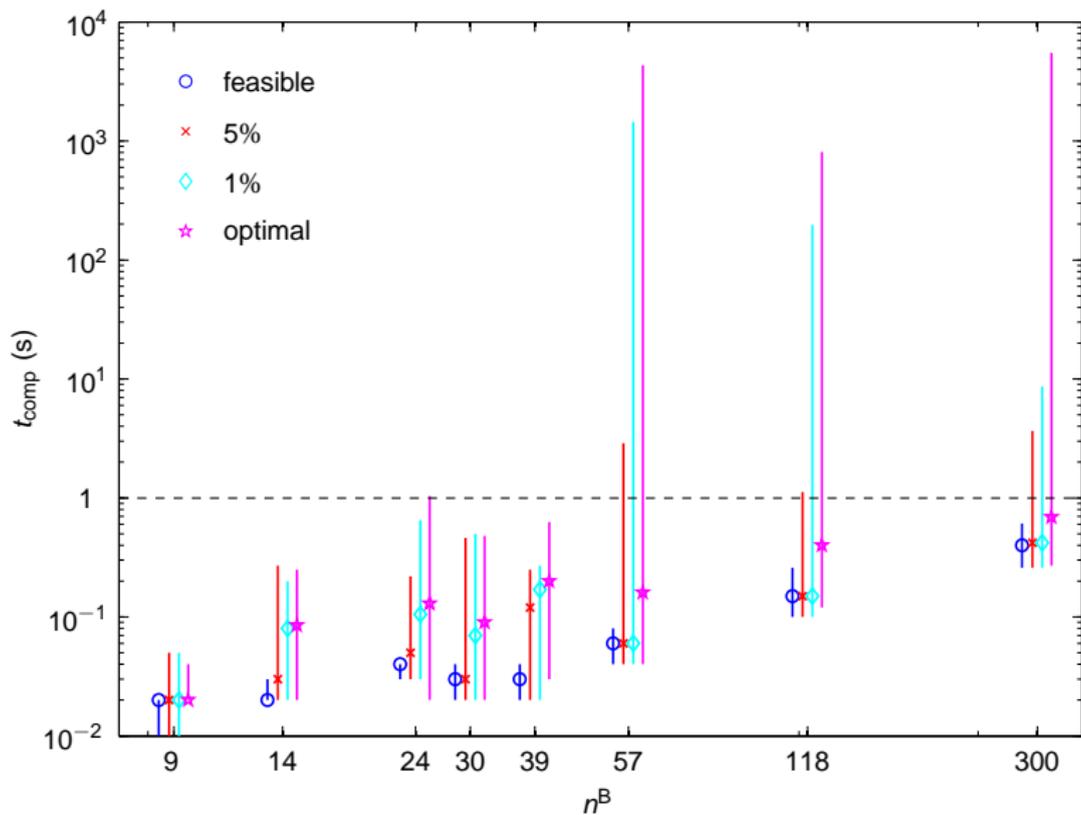
1. Solve OPF: for pre-islanded state using the full AC equations.
2. Based on this solution solve the MILP problem to decide the best islands and generator shut downs.
3. With the islands and generator shutdowns fixed, solve an optimal load shedding problem using the full AC equations.

Software and examples

- ▶ 1 and 3 use IPOPT (COIN-OR).
- ▶ 2 uses CPLEX 12.3 (using 8 cores)
- ▶ IEEE test cases up to 300 buses.

Computational Times (DC constant loss)

Min, Median and Max



MILP Suboptimality (DC constant loss)

How close is the MILP solution to the MILP optimal?

Much better than the bounds indicate:

Average amount above proven optimal solution

Feasible	5% gap	1% gap
9.12%	0.37%	0.04%

AC infeasibility (DC constant loss)

- ▶ Some AC solutions were infeasible because voltage limits were violated.
- ▶ Proportion where one or more methods gave an AC infeasibility:

n^B	9	14	24	30	39	57	118	300
AC infeasible %	0%	15%	50%	27%	35%	17%	14%	28%

What can be done?

- ▶ Relaxing voltage limits in the contingency?
 $0.9 \leq v \leq 1.1$ “cures” some cases.
- ▶ Alter the tap setting post-islanding?
- ▶ Use AC PWL in MILP for islanding

AC feasibility problems

DC constant loss MILP

Voltage problems

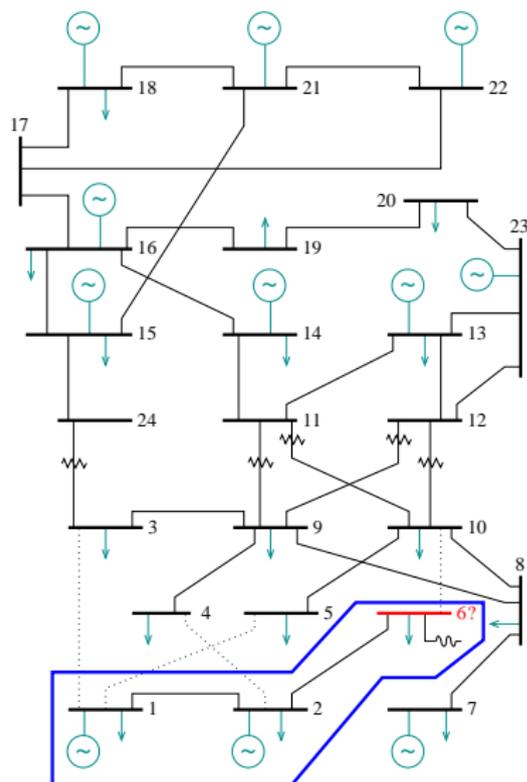
$$V_2 = 1.1461$$

$$V_6 = 0.8452$$

Disconnect static reactor at bus 6:

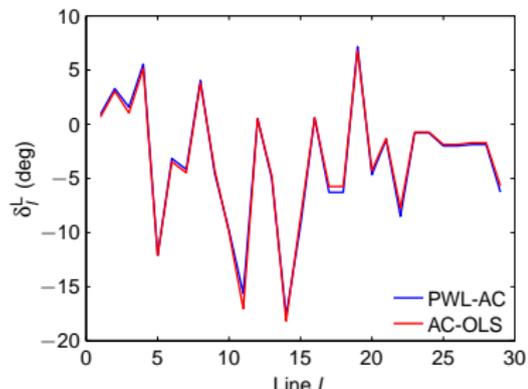
$$V_2 = 1.0709$$

$$V_6 = 0.9291$$

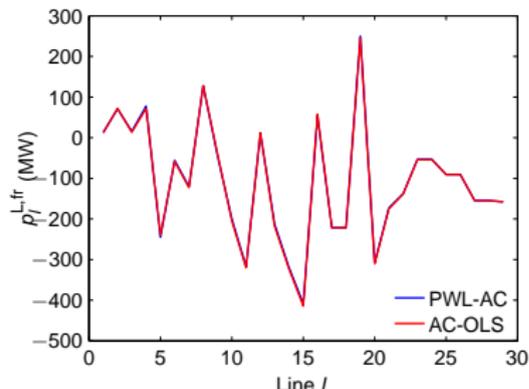


Comparison of AC PWL and AC solutions

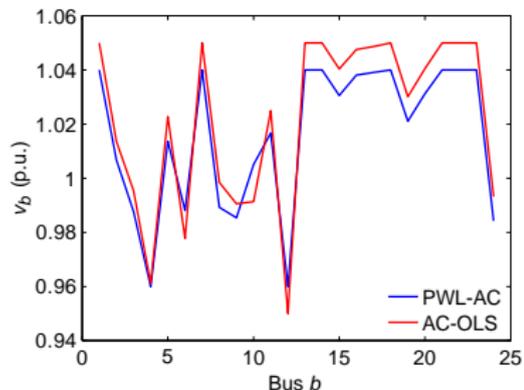
24-bus network: angles, voltages & flows



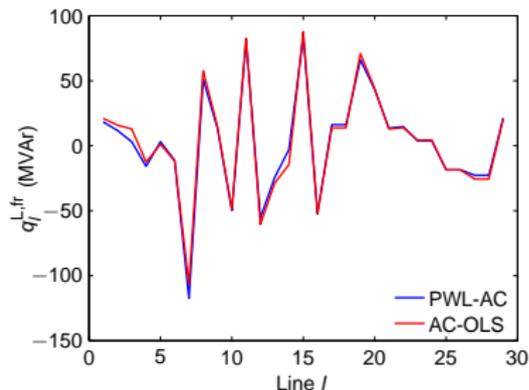
(a) Angle differences



(b) Real flows



(c) Voltages



(d) Reactive flows

AC Infeasible cases

24 Bus case. 24 single bus contingencies

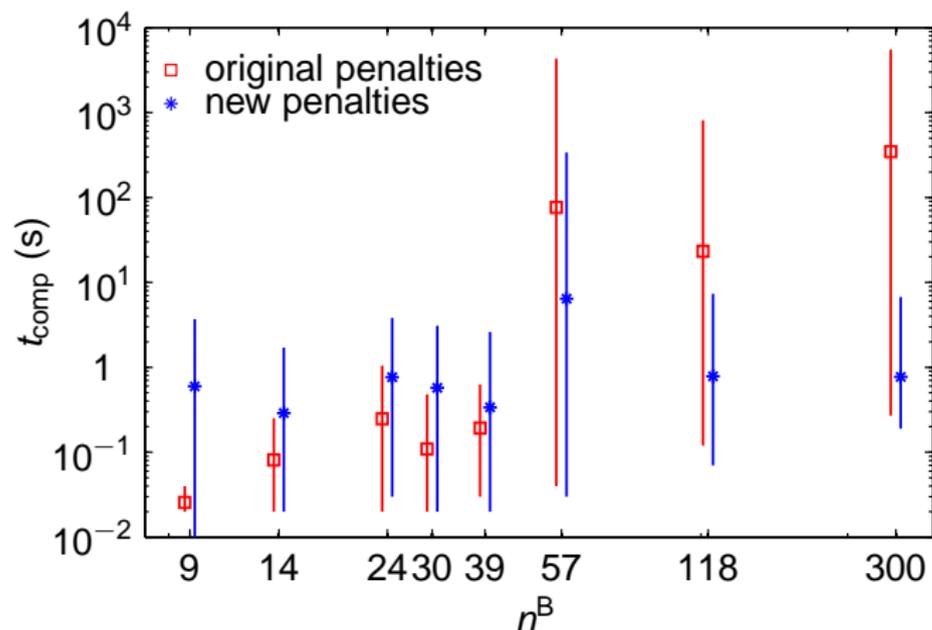
Method	Number AC infeasible	Average Elapsed Time (sec)
DC Constant	7	0.32
AC Linear	3	2.33
AC PWL	0	7.61

Results are similar for other IEEE cases

Dynamic instability

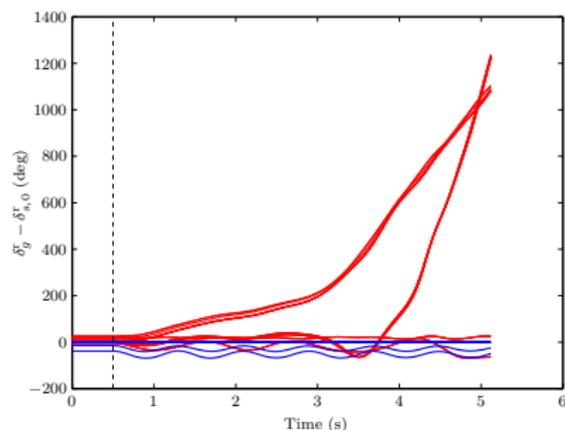
- ▶ Islanding creates a shock that could excite dynamic instability, and so prevent the system converging to the planned steady state.
- ▶ Tests of previous 452 islanding solutions using 2nd order models showed **14 to be transiently unstable**.
- ▶ Penalise line and generator disconnections to reduce shock

Times with and without line and generator penalties

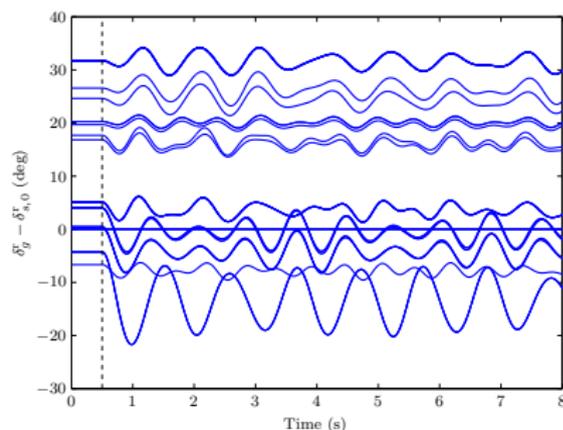


- ▶ All problems now transiently stable
- ▶ Average load supply decreased by 0.34%

Note different scales



Low penalty - Unstable
 Predicted load supplied
 = 2707 MW
 25 generators lose synchrony
 — all in “safe” section



High penalty - Stable
 Predicted load supplied
 = 2675 MW
 No loss of synchrony

Current & Future

- ▶ **Scale up:** We can solve “2500” bus Polish networks with DC MILP
- ▶ **Computation:** Develop heuristics and aggregation methods
- ▶ **Bus splitting:** to give more flexibility in islanding.
- ▶ **Dynamic stability:** Incorporate more realistic indicators in MILP
— using work being done at Durham.

Thank You

Questions?